

KITS Workshop on “Machine Learning and Many-Body Physics”

# Sparse modeling: how to solve the ill-posed problem

Graduate School of Information Sciences  
Tohoku University

Masayuki OHZEKI

CREST

*Sparse Modeling*



QUANTUM  
ANNEALING



MACHINE  
LEARNING

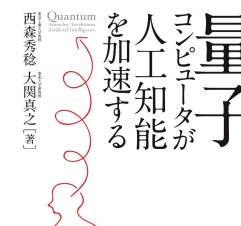


**TOHOKU**  
UNIVERSITY



# Self Introduction

- ▶ Masayuki Ohzeki (大関真之)
  - ▶ Tohoku University [2016.10-]
  - ▶ Kyoto University [2010.05-2016.09]
    - ▶ Machine learning: Sparse modeling and Deep learning
  - ▶ Tokyo Institute of Technology [2008.10-2010.04]
    - ▶ Physics: Statistical Mechanics and Quantum annealing



大関真之



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ANNEALING



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# Me in Japan... Cheating OHZEKI ?

- ▶ Mar. 27. 2015:NHK 「Good morning Japan」





# **Recent advance in news and media**



Recent advance  
in news and media

A. I. ?



Recent advance  
in news and media  
**Inverse problem**

$$y = f(\mathbf{x})$$



Recent advance  
in news and media  
Inverse problem

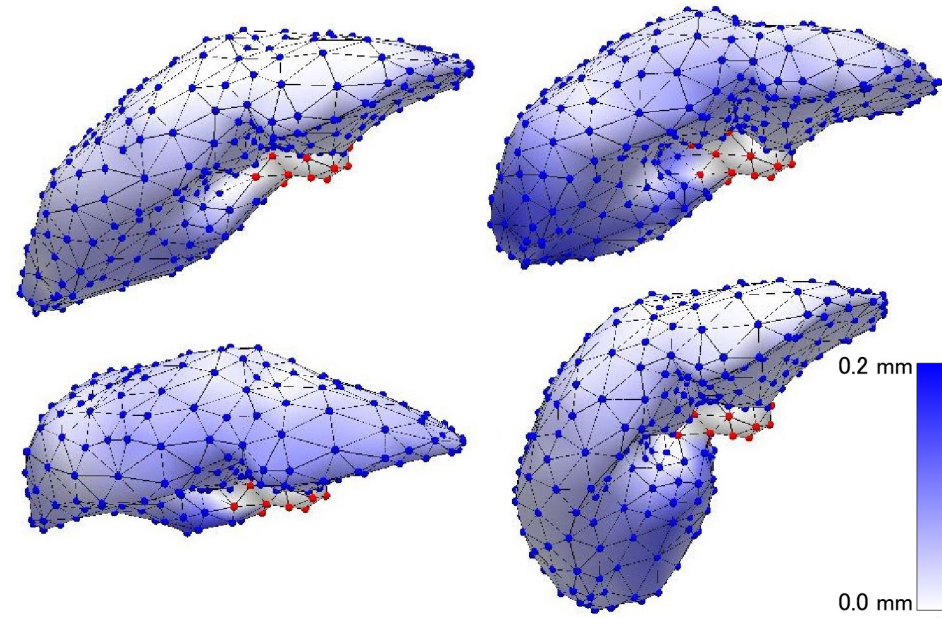
$$y = f(\mathbf{x})$$



# Estimation for deformation in body

Collaboration with U. Yamamoto, M. Kaneko, T. Matsuda (Kyoto Univ.) submitted

- ▶ Inference from a limited range of data
  - ▶ Learning the rule of the dynamics
  - ▶ Observation 9 points • unobserved 295 points
  - ▶ Inference of the deformation by pulling 4cm
  - ▶ (average of RMSE **0.035mm!**)

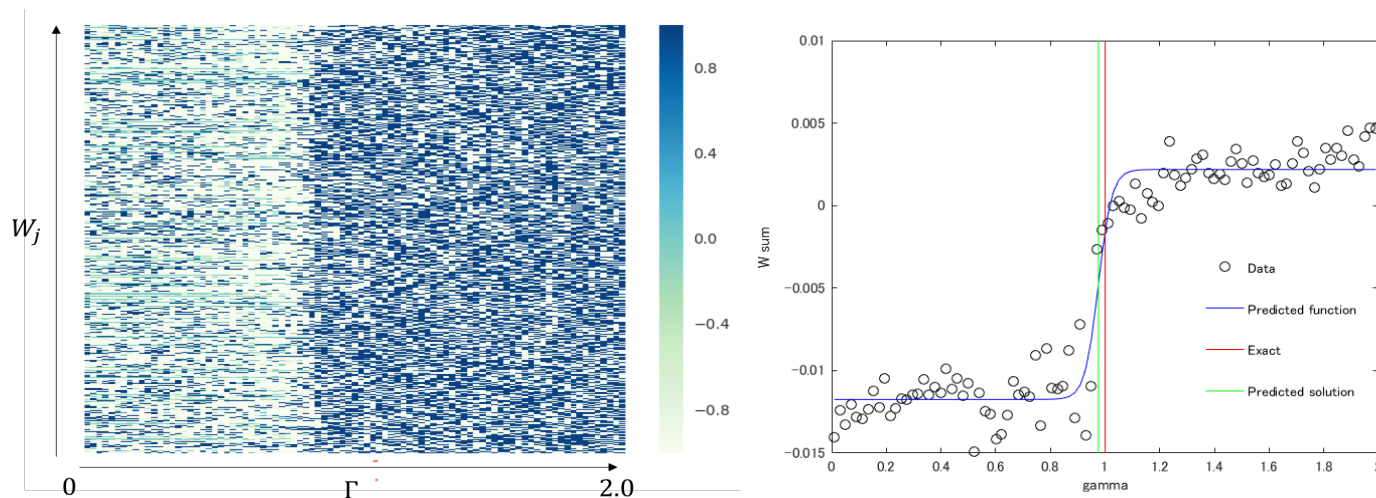




# Detecting the phase transition

Collaboration with S. Arai (Tohoku Univ.) to appear soon

- ▶ Original work done by Tanaka and Tomiya (2017)
  - ▶ Learning from snapshots of the Ising model
  - ▶ Detection of the second-order phase transition from **weights**
- ▶ Extension of their work
  - ▶ Learning from snapshots of the XY/quantum Ising model
  - ▶ Detection of the Kosterlitz-Thouless transition
  - ▶ Detection of the second-order phase transition in quantum system







From Purchase data, Customer service  
**Am○zon**









Recent advance  
in news and media

Inverse problem

$$y = f(\mathbf{x})$$

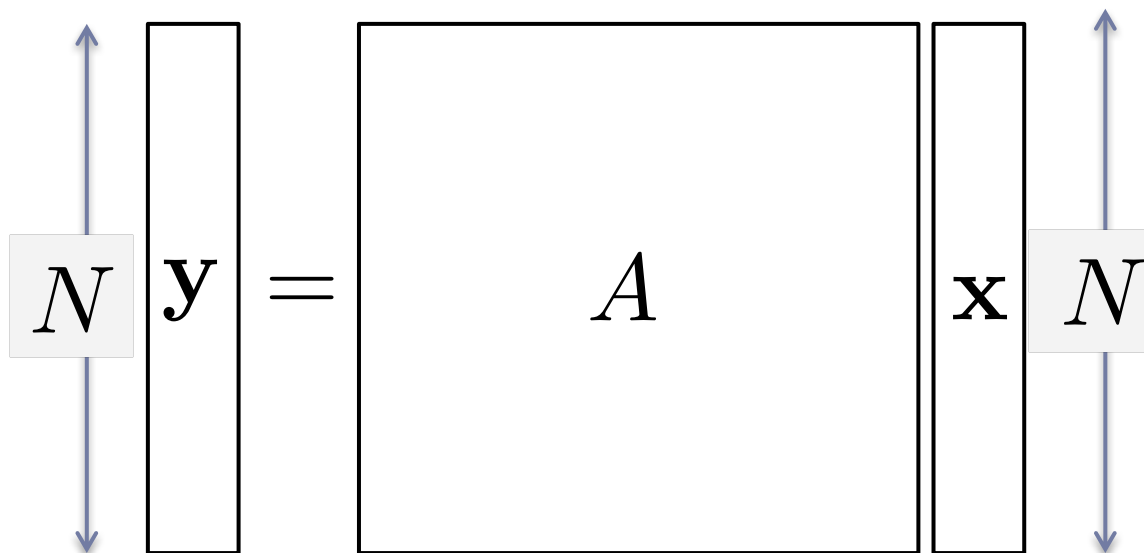


Recent advance  
in news and media

Inverse problem

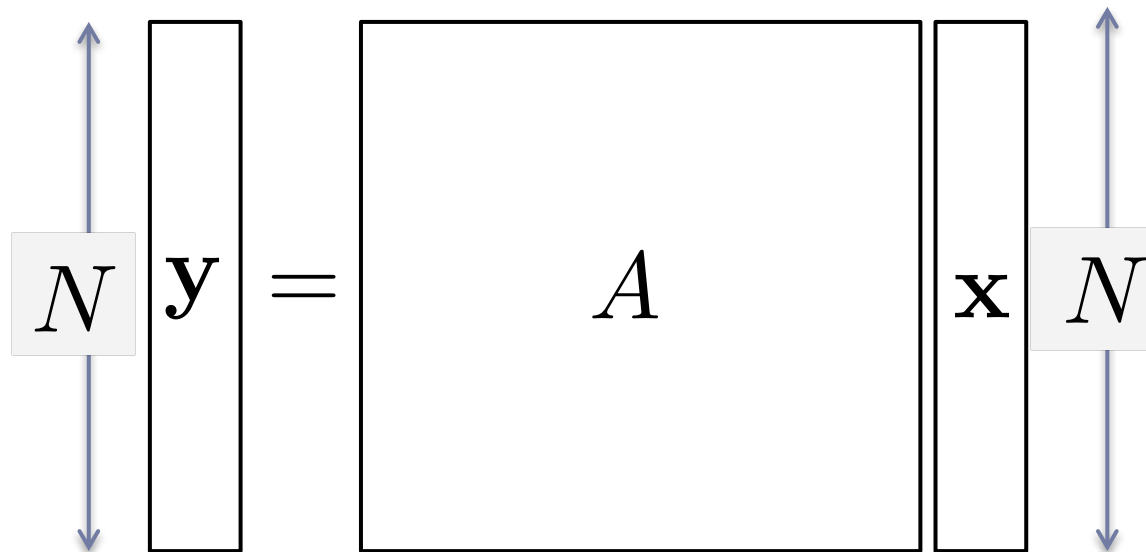
$$y = f(\mathbf{x})$$





$$\mathbf{y} = \mathbf{A}\mathbf{x}$$

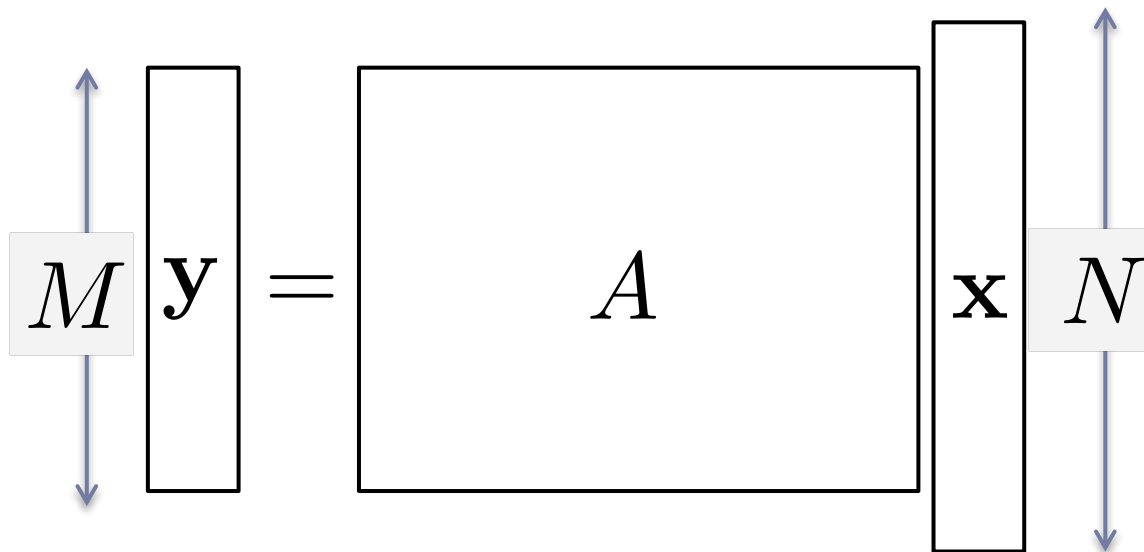




$$\mathbf{y} = \mathbf{A}\mathbf{x}$$

**Multiplication of inverse of  $\mathbf{A}$**

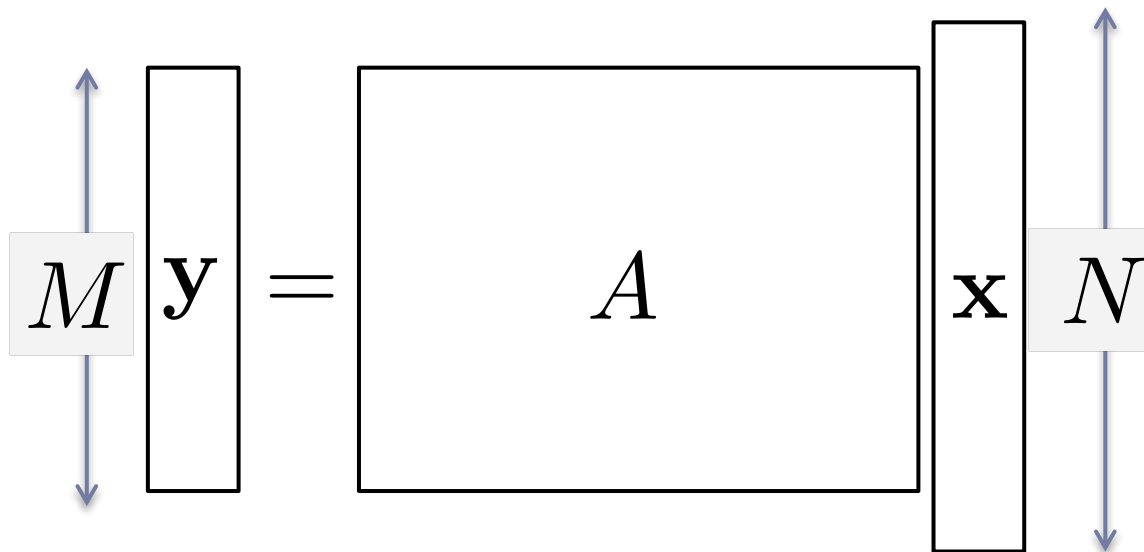




$$y = Ax$$

**In this case?**

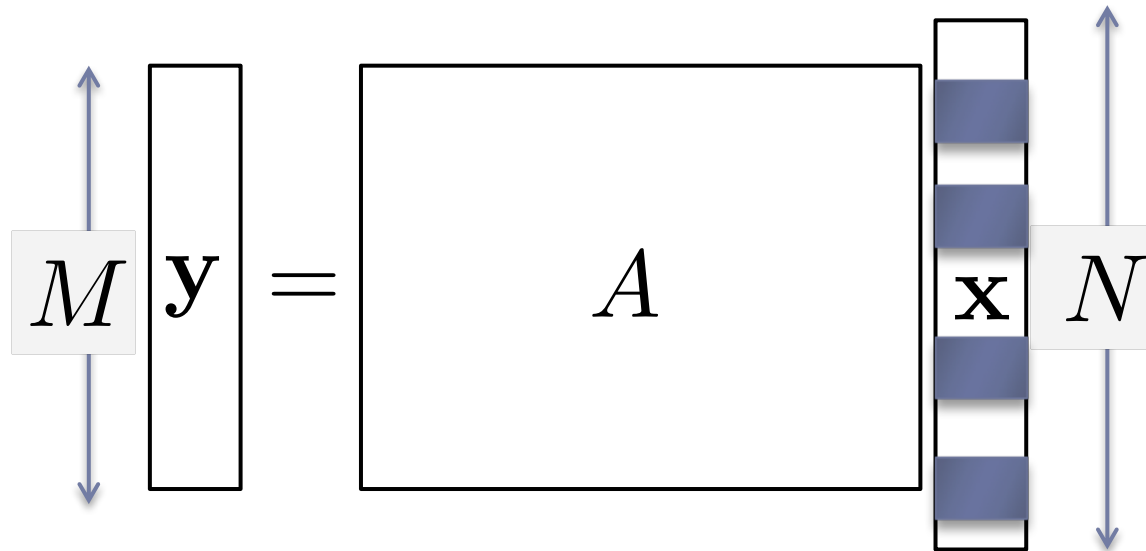




$$y = Ax$$

**No inverse matrix**

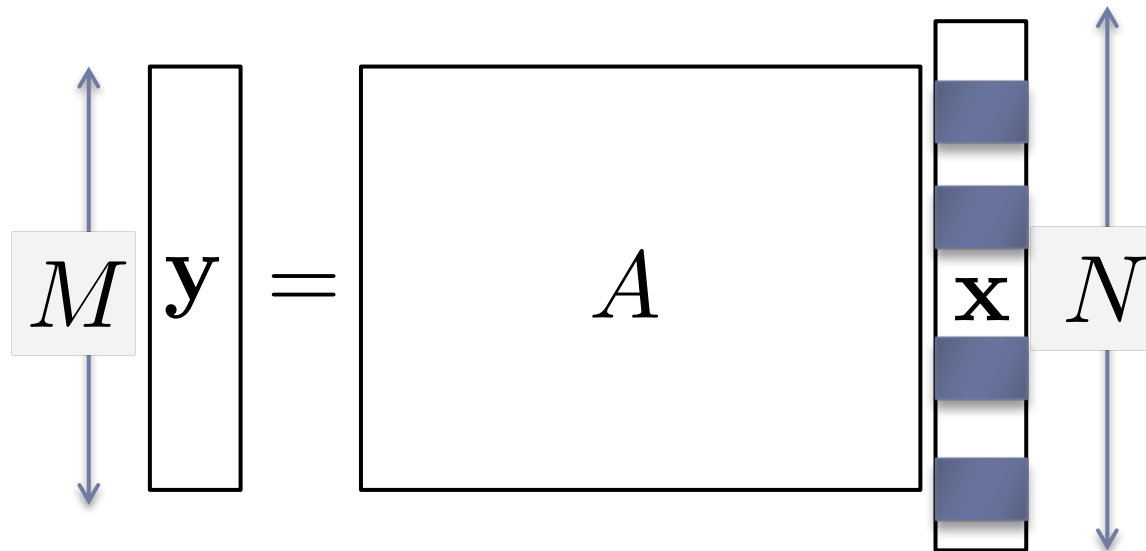




$$y = Ax$$

In the case with **sparse** solution



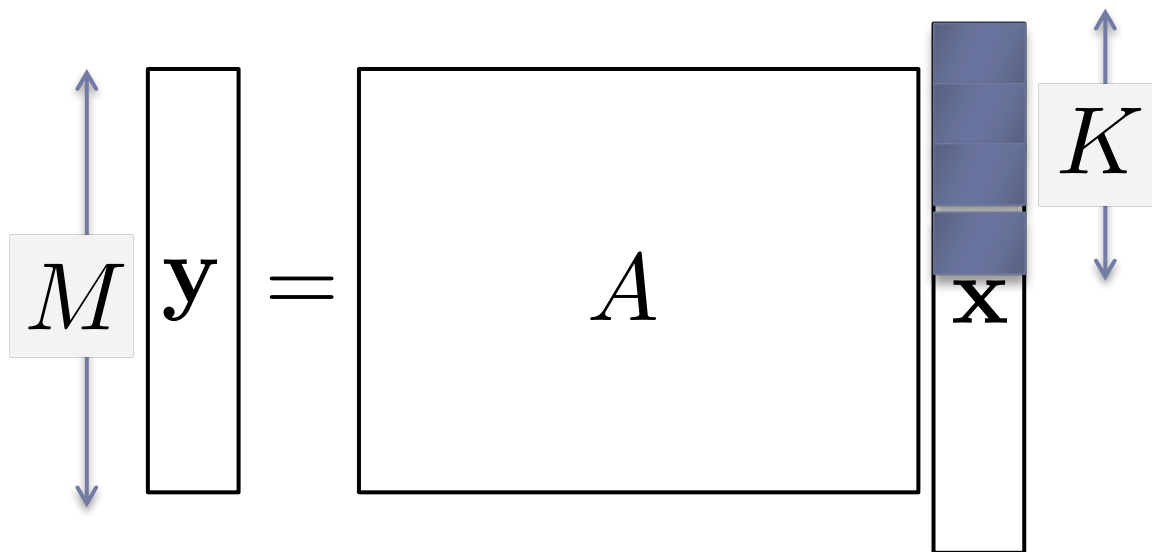


$$y = Ax$$

In the case with **sparse** solution

**We can**



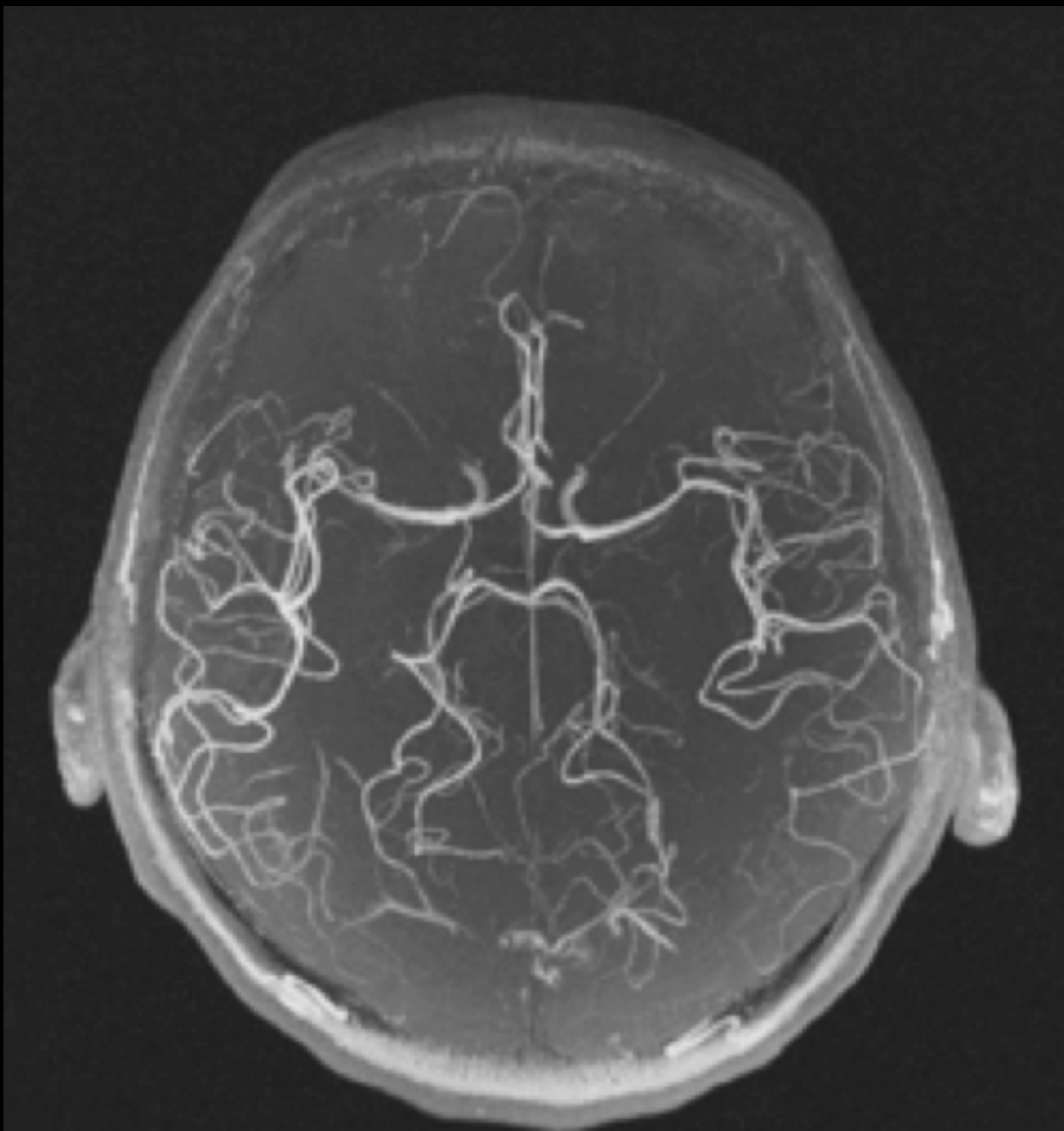


$$y = Ax$$

In the case with **sparse** solution

**We can**

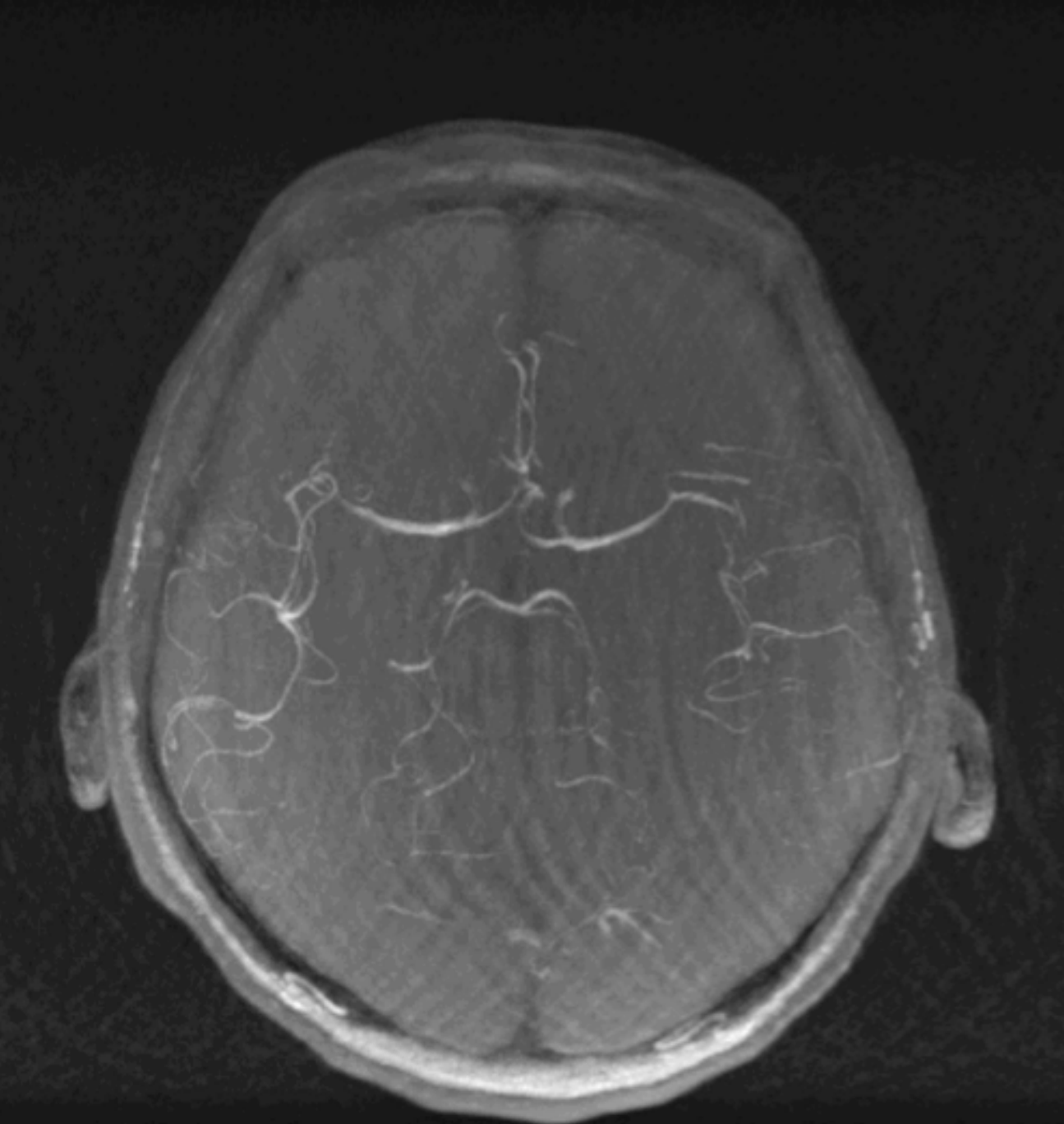




Collaboration with Kyoto University

Example of MRI

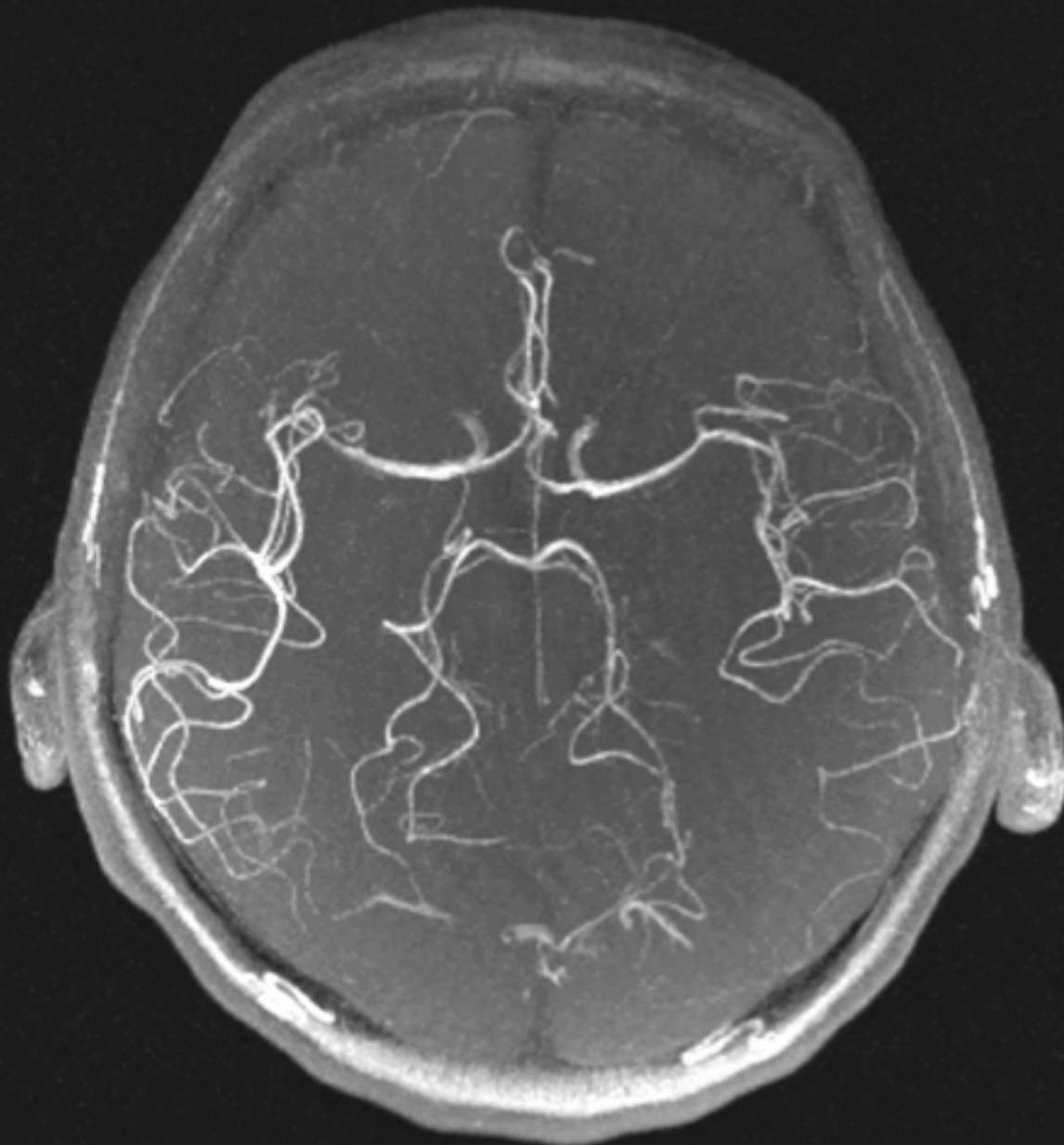




Collaboration with Kyoto University

Low amount of data





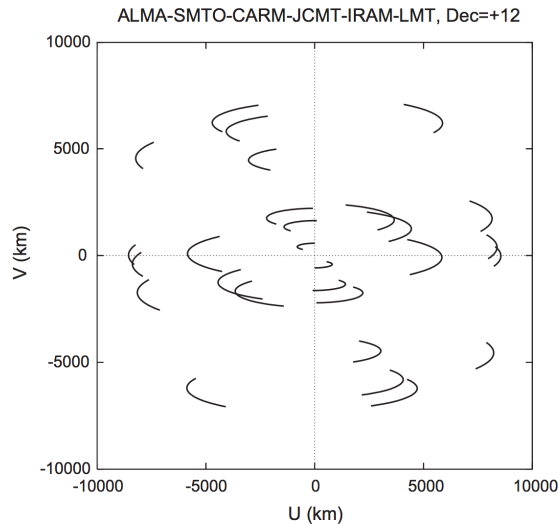
Collaboration with Kyoto University

Compressed sensing

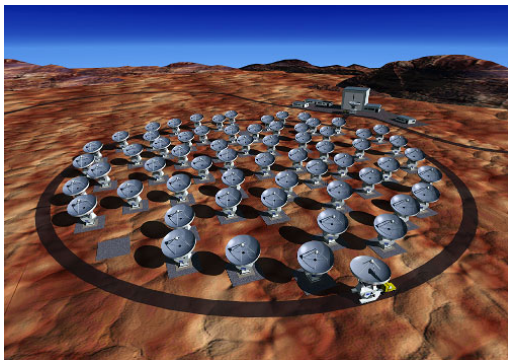


# Astrophysics and Sparse modeling

K. Akiyama, et al. *Astrophys. J.* (2017)



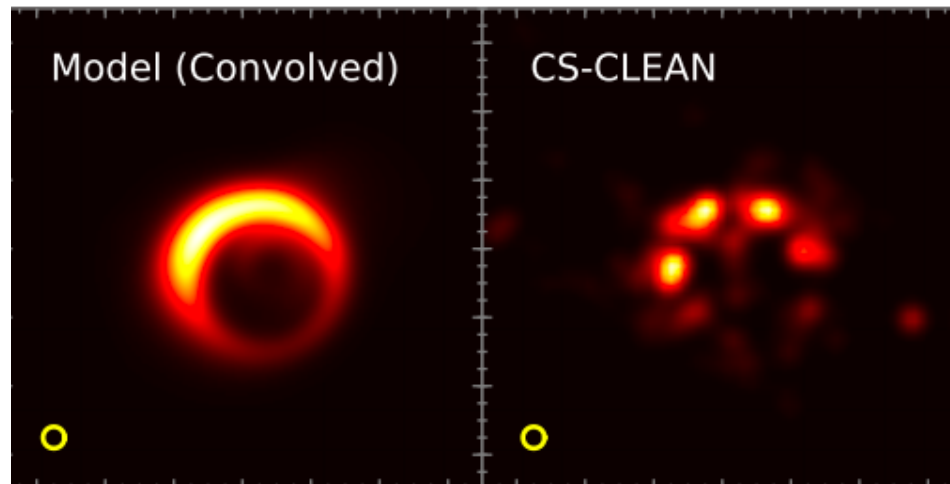
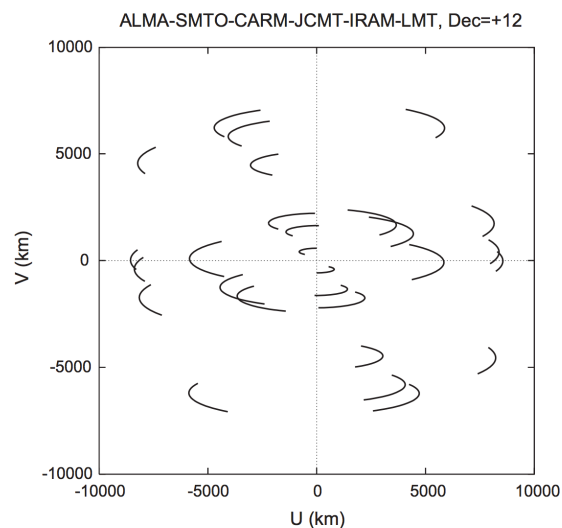
**Fig. 5.** Simulated UV coverage of M87 with six-station sub-mm VLBI array of EHT. Here it is assumed that observations are conducted at an elevation larger than  $20^\circ$  at each station.



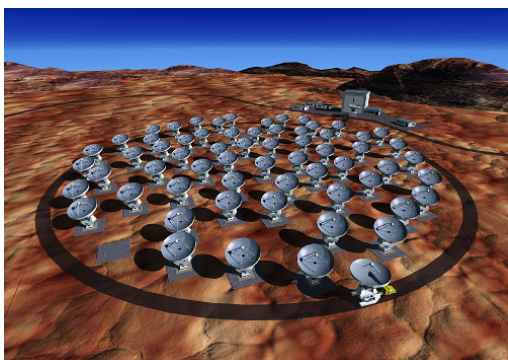


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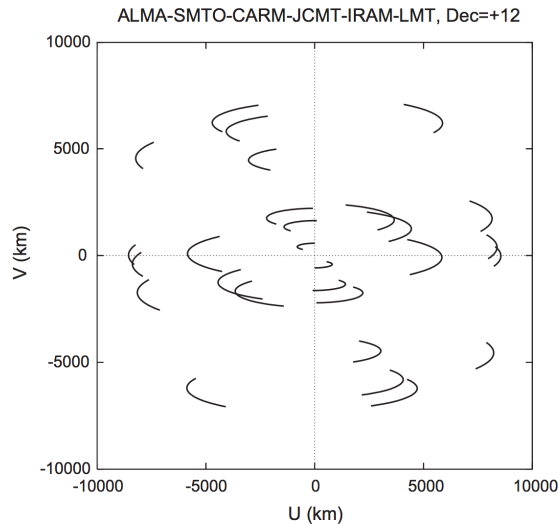
**Fig. 5.** Simulated UV coverage of M87 with six-station sub-mm VLBI array of EHT. Here it is assumed that observations are conducted at an elevation larger than  $20^\circ$  at each station.



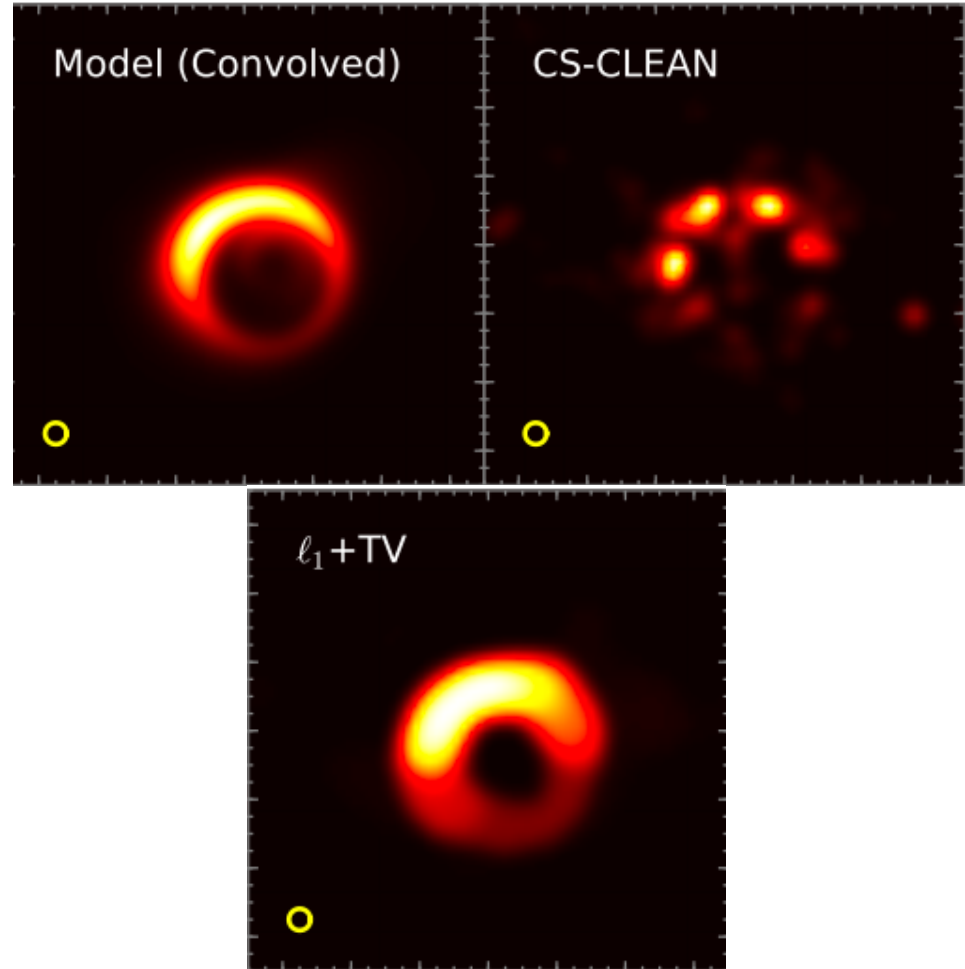
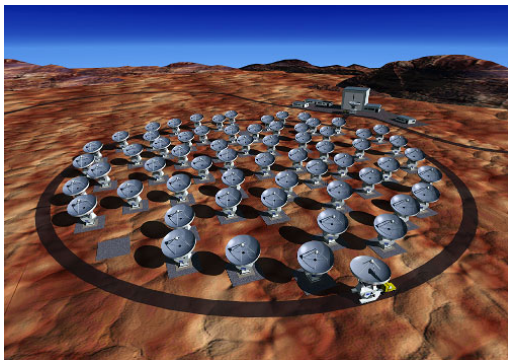


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**Fig. 5.** Simulated UV coverage of M87 with six-station sub-mm VLBI array of EHT. Here it is assumed that observations are conducted at an elevation larger than  $20^\circ$  at each station.

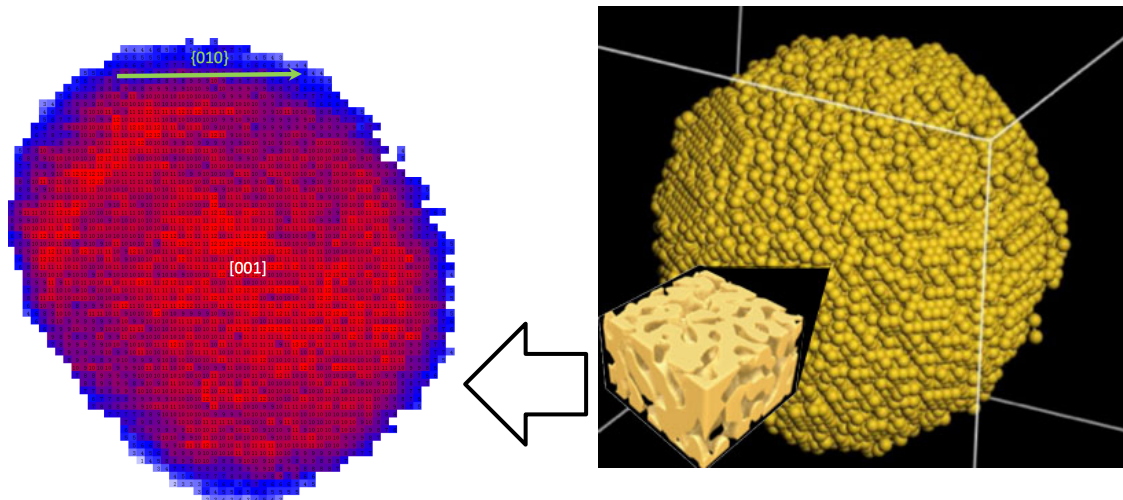




# Material and Sparse modeling

Collaboration with C. Nakajima (Tohoku univ.)

- ▶ HAADF-STEM
- ▶ Projection mapping

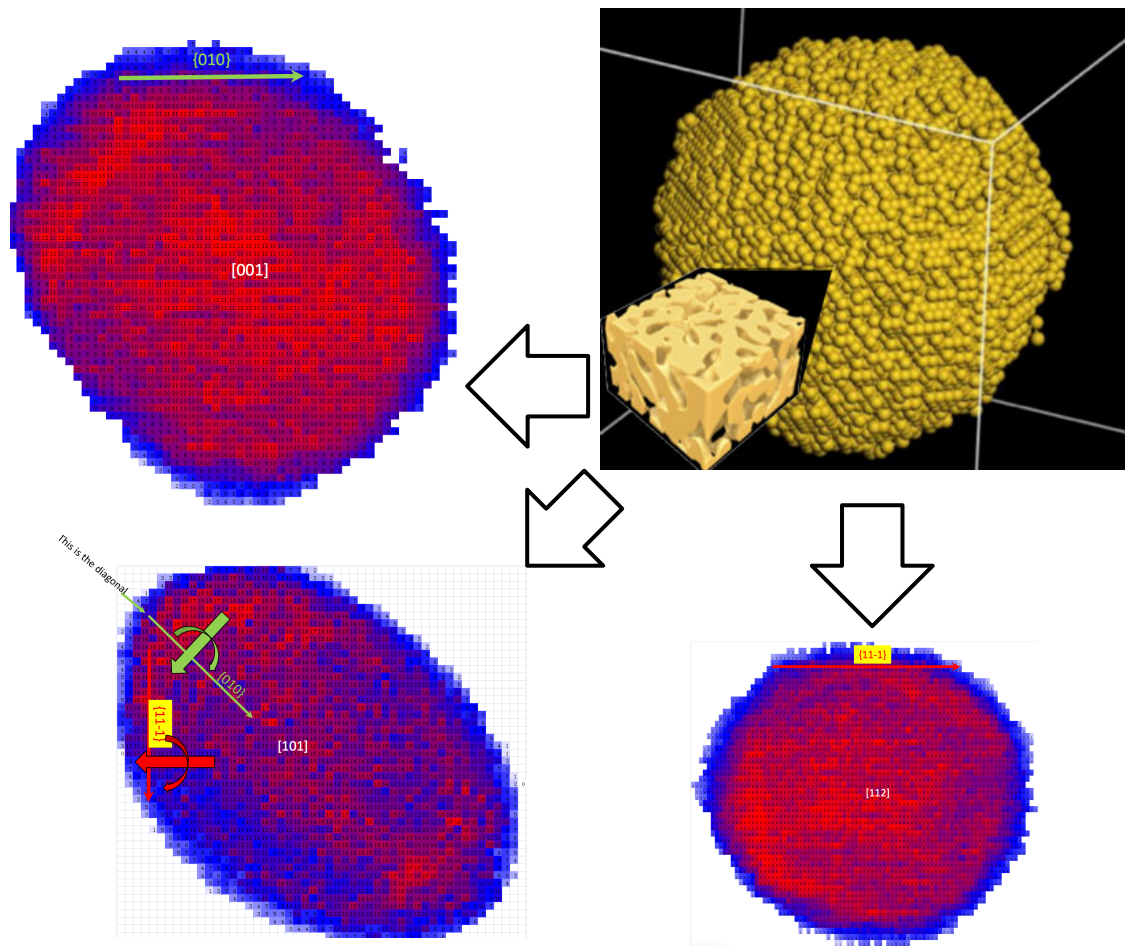




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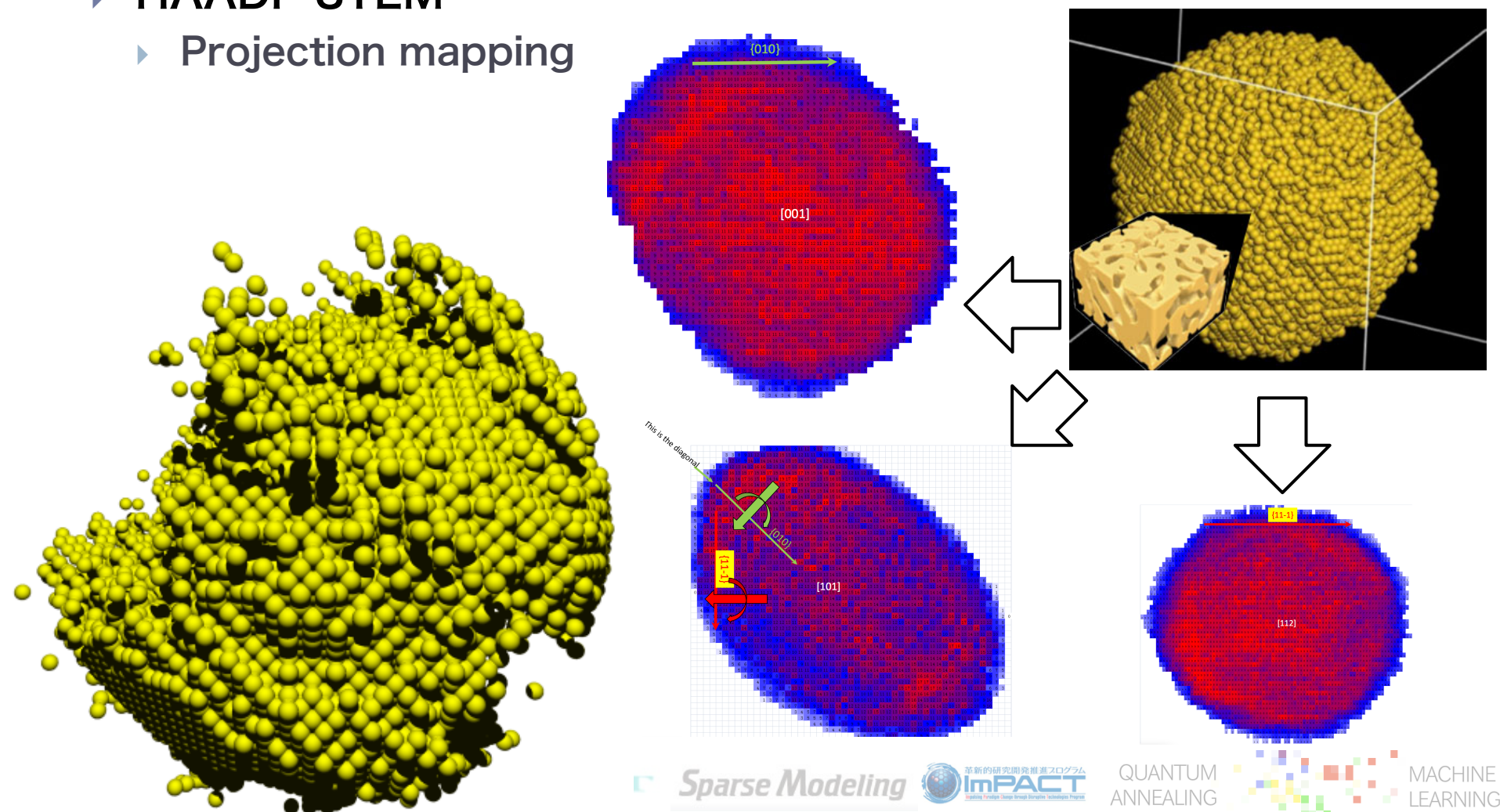




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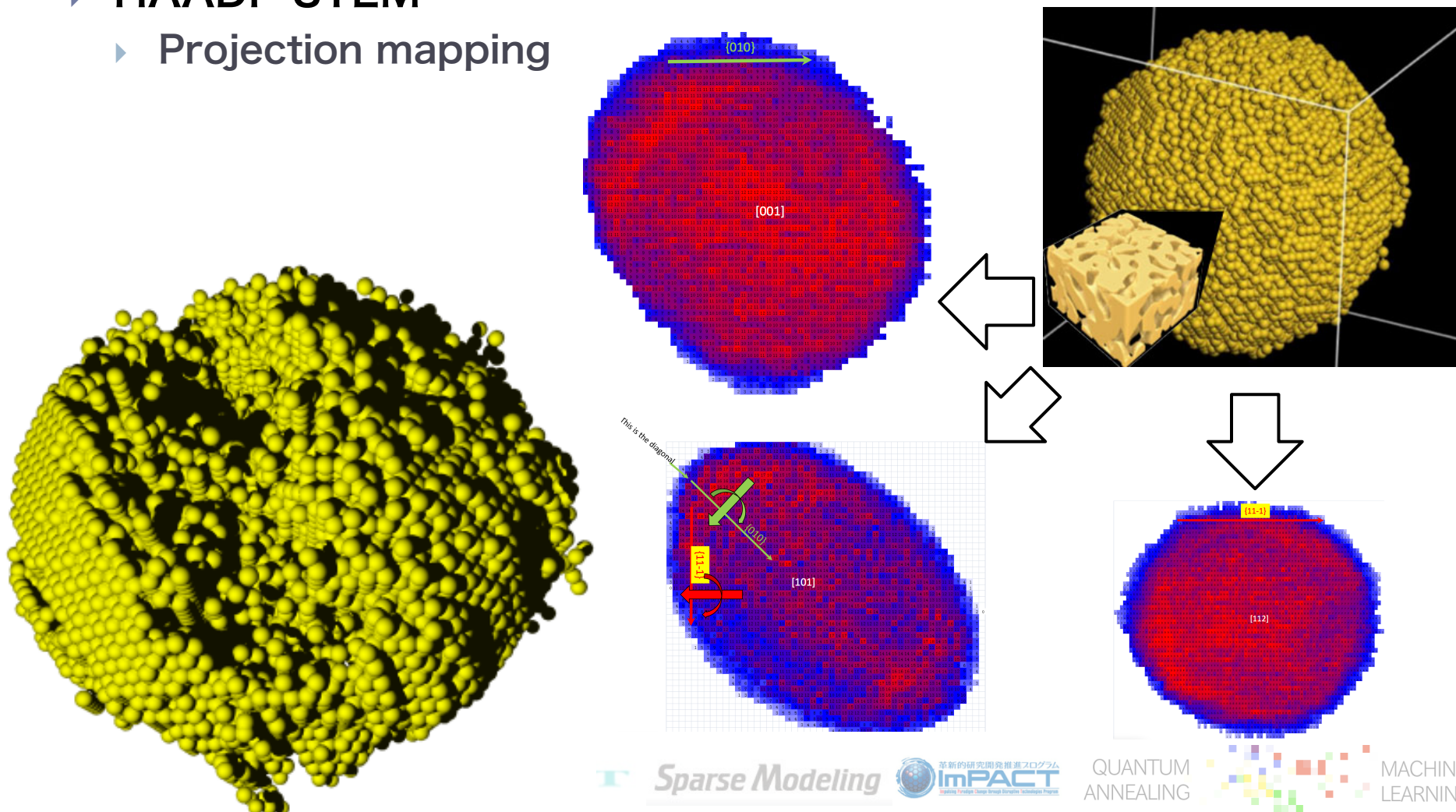




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Sparse Modeling



革新的研究開発推進プログラム  
ImPACT  
Innovative Materials Project

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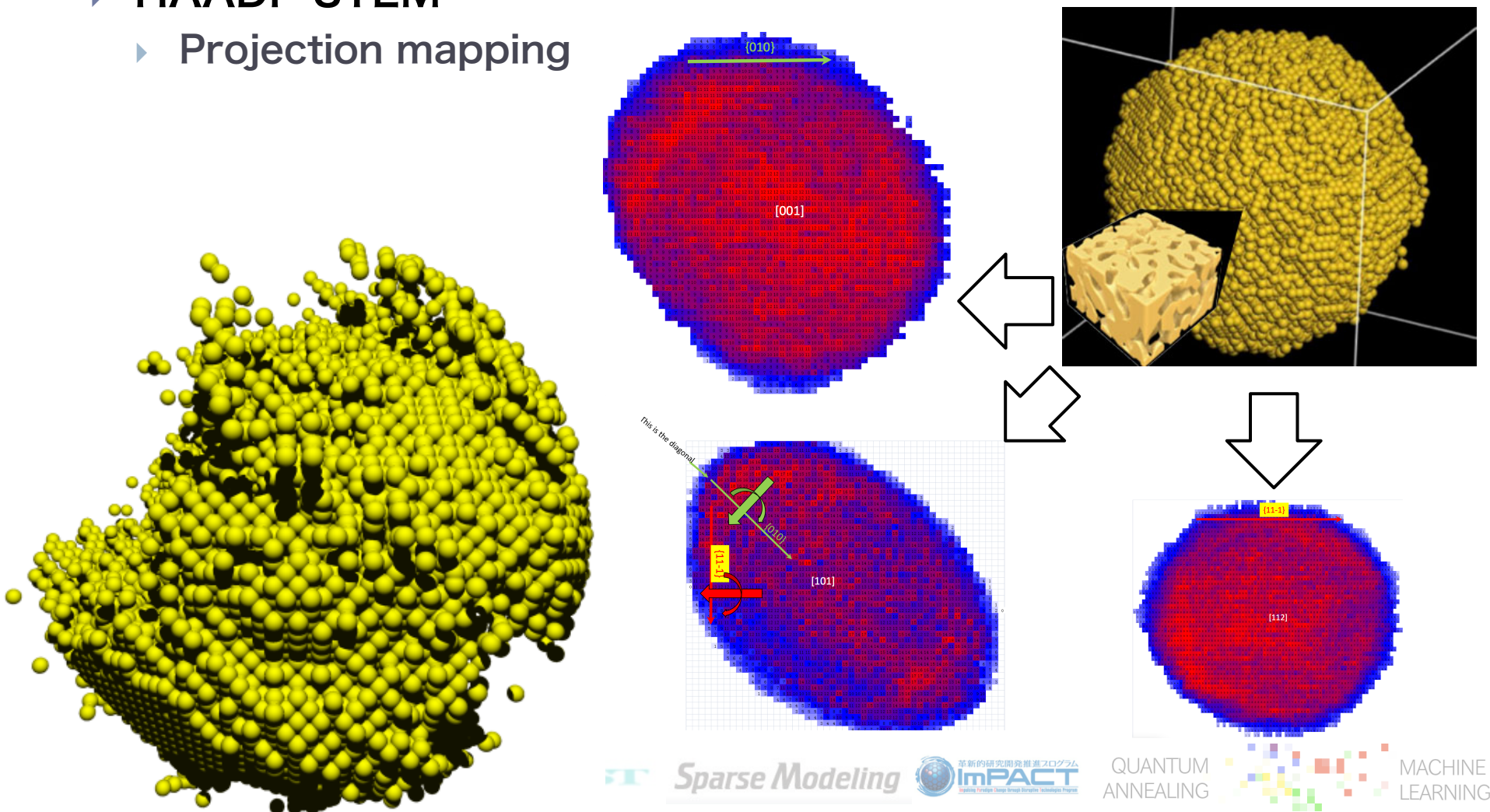
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LEARNING



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Sparse Modeling



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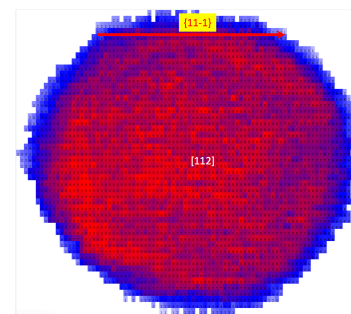
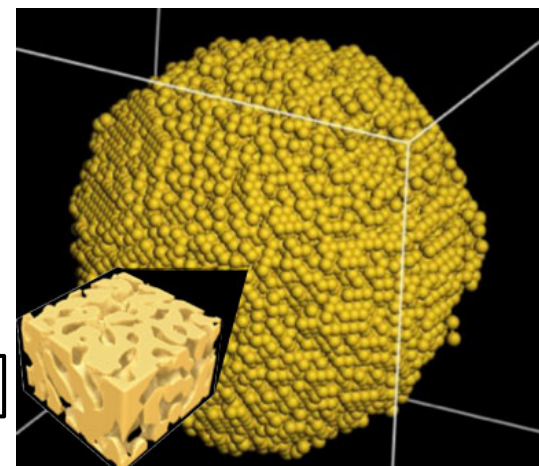
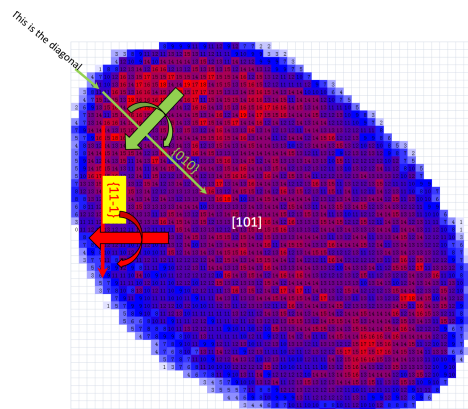
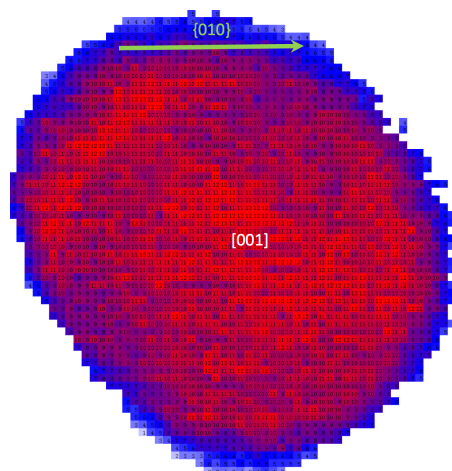
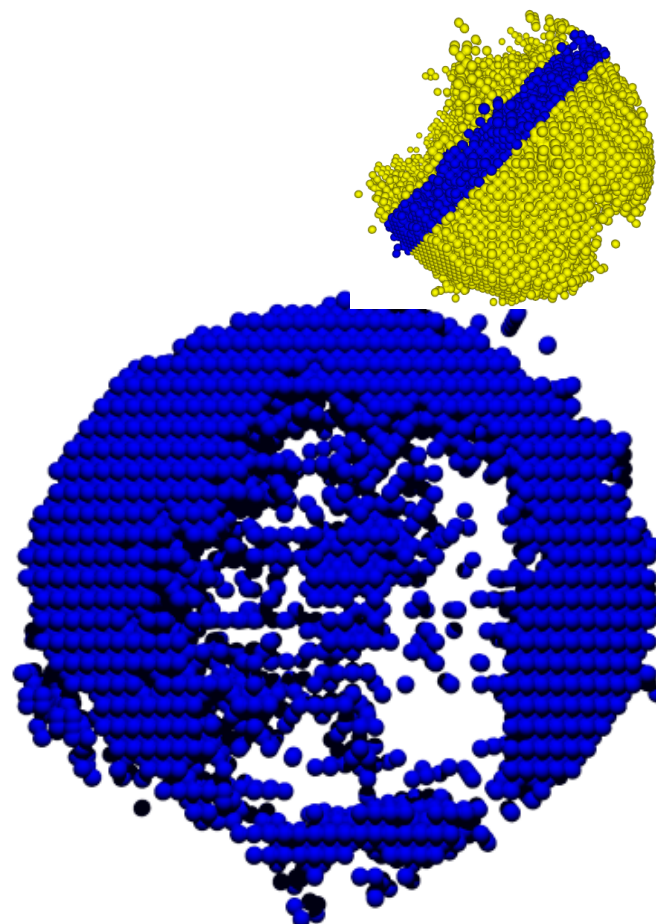
MACHINE  
LEARNING



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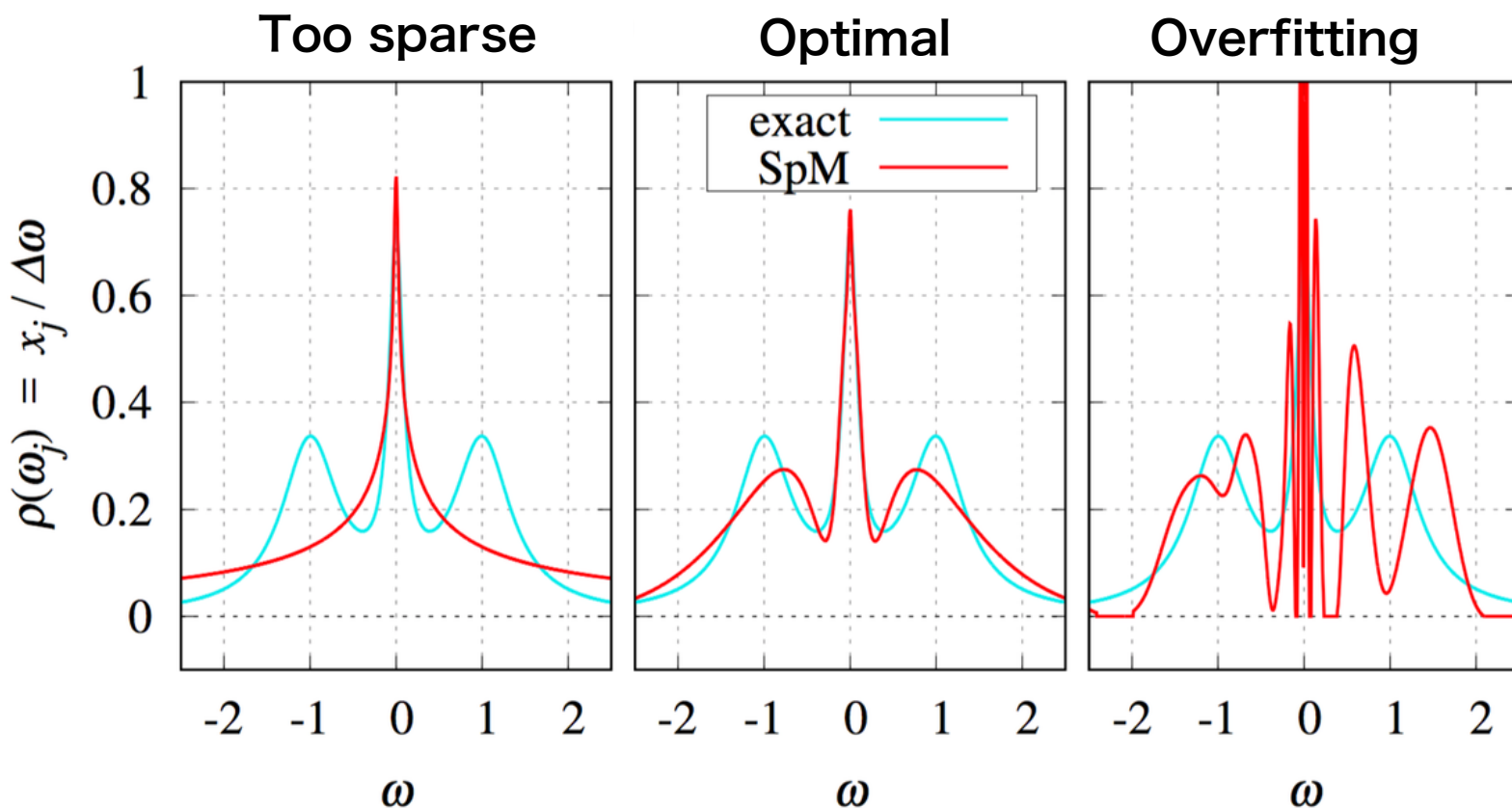




# Analytical continuation in QMC

J. Otsuki, M. Ohzeki, H. Shinaoka, and K. Yoshimi: Phys. Rev. E 95, 061302(R) (2017)

- Results for single-impurity Anderson model
  - Solving  $\mathbf{G} = \mathbf{K}\rho$  by use of maxEnt? No!!





**Lack of information but inference**  
**Compressed sensing**



# Sparse signal inference

- ▶ L0 norm minimization
  - ▶ The following optimization problem

$$\min_{\mathbf{x}} \|\mathbf{x}\|_0 \quad \text{s.t.} \quad \mathbf{y} = A\mathbf{x}$$



# Sparse signal inference

- ▶ L0 norm minimization
  - ▶ The following optimization problem

$$\min_{\mathbf{x}} \|\mathbf{x}\|_0 \quad \text{s.t.} \quad \mathbf{y} = A\mathbf{x}$$

- ▶ L0 norm = number of nonzero elements



# Sparse signal inference

- ▶ L0 norm minimization
  - ▶ The following optimization problem

$$\min_{\mathbf{x}} \|\mathbf{x}\|_0 \quad \text{s.t.} \quad \mathbf{y} = A\mathbf{x}$$

- ▶ L0 norm = number of nonzero elements
  - ▶ Sparse solution
  - ▶ **Non-Convex optimization**
  - ▶ Exponential computational cost (**exp(N)**)



# Sparse signal inference

- ▶ **L1** norm minimization
  - ▶ Much easier optimization problem

$$\min_{\mathbf{x}} \|\mathbf{x}\|_1 \quad \text{s.t.} \quad \mathbf{y} = A\mathbf{x}$$

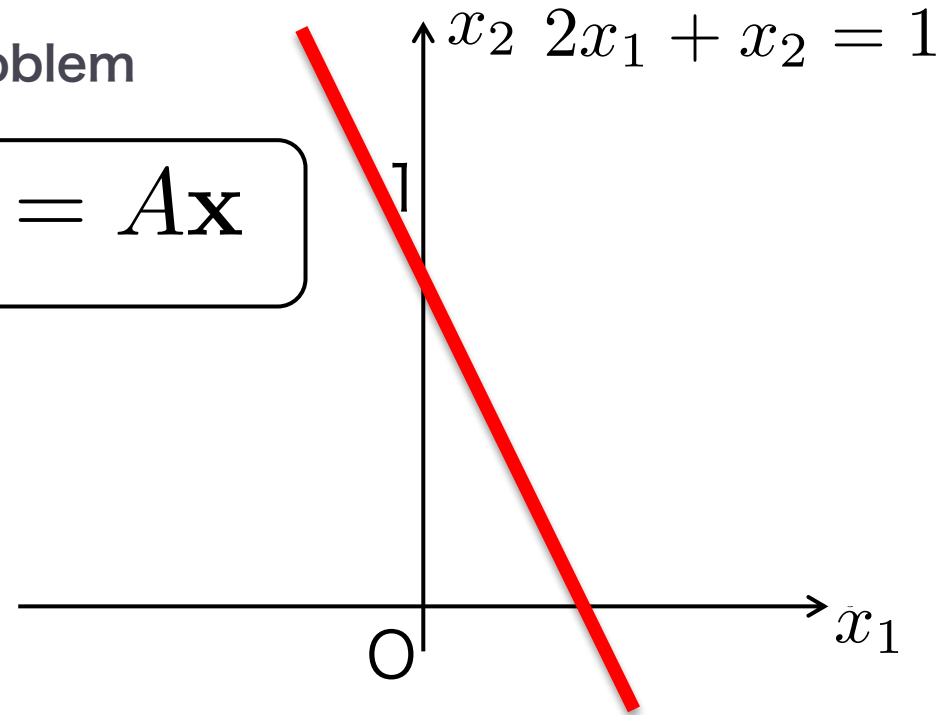
$$\|\mathbf{x}\|_1 = |x_1| + |x_2| + \cdots + |x_N|$$



# Sparse signal inference

- ▶ **L1** norm minimization
  - ▶ Much easier optimization problem

$$\min_{\mathbf{x}} \|\mathbf{x}\|_1 \quad \text{s.t.} \quad \mathbf{y} = A\mathbf{x}$$



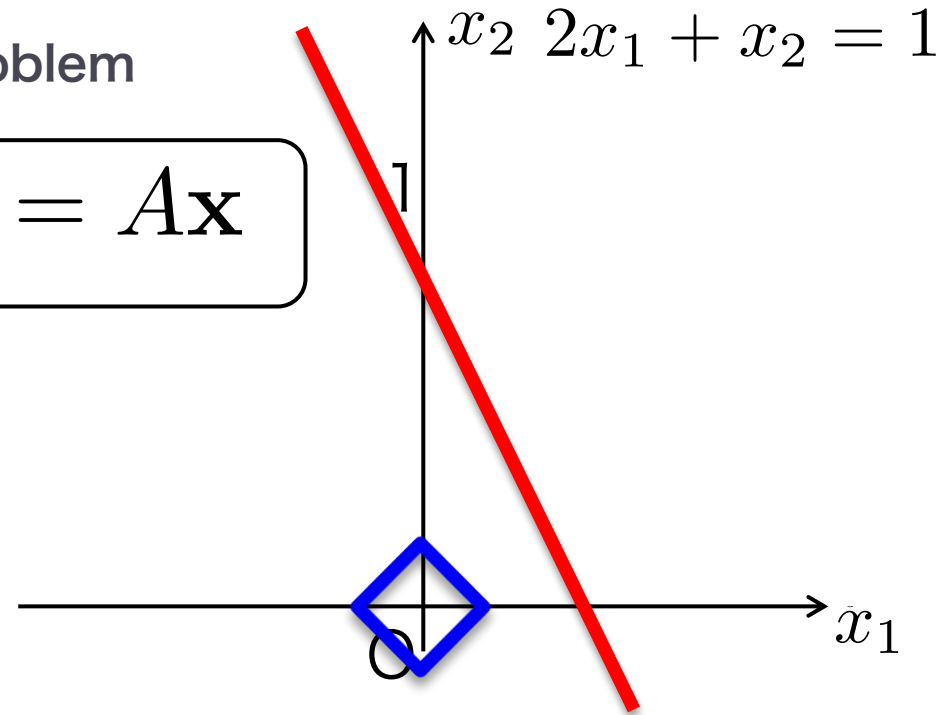
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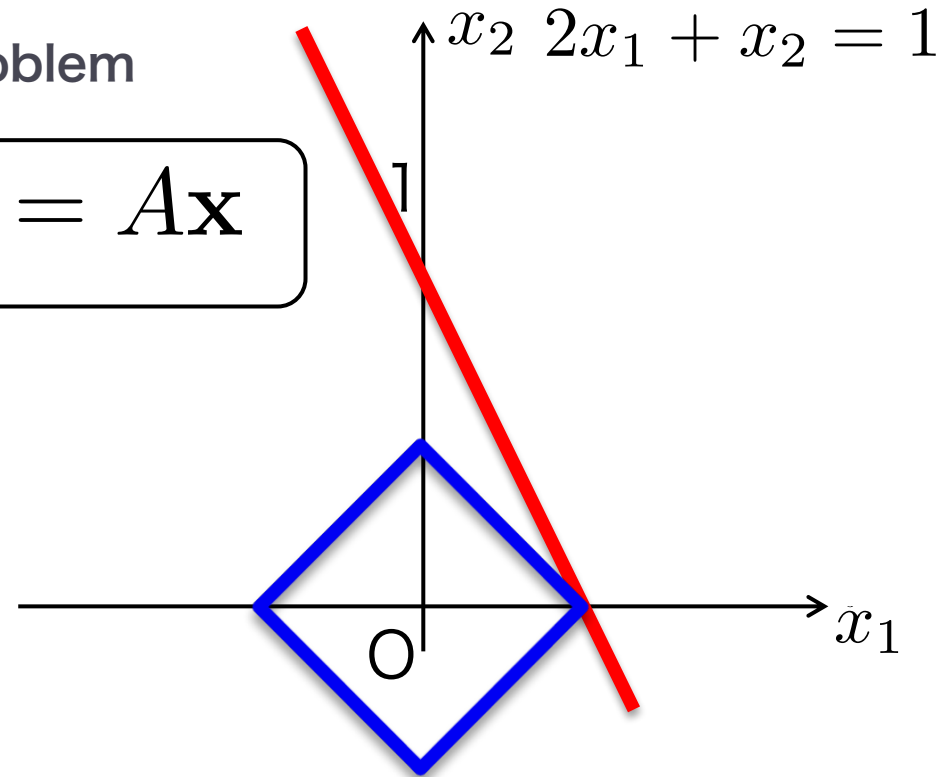
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$$\|\mathbf{x}\|_1 = |x_1| + |x_2| + \cdots + |x_N|$$

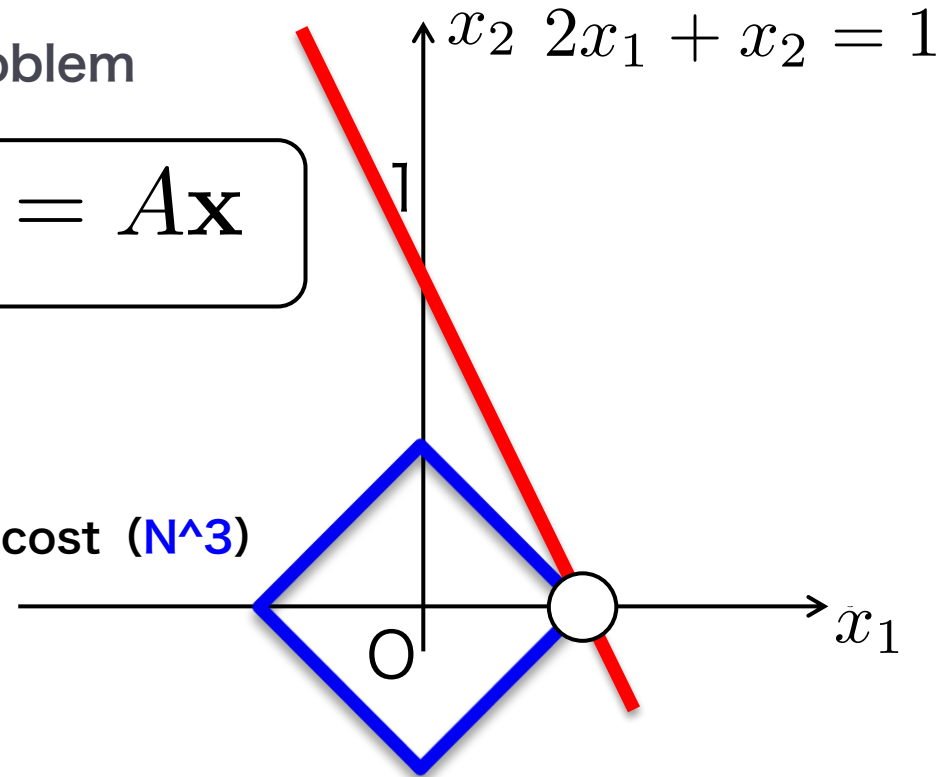


# Sparse signal inference

- ▶ **L1** norm minimization
  - ▶ Much easier optimization problem

$$\min_{\mathbf{x}} \|\mathbf{x}\|_1 \quad \text{s.t.} \quad \mathbf{y} = \mathbf{A}\mathbf{x}$$

- ▶ Sparse solution
- ▶ **Convex optimization**
- ▶ Not expensive computational cost ( $N^3$ )



$$\|\mathbf{x}\|_1 = |x_1| + |x_2| + \cdots + |x_N|$$

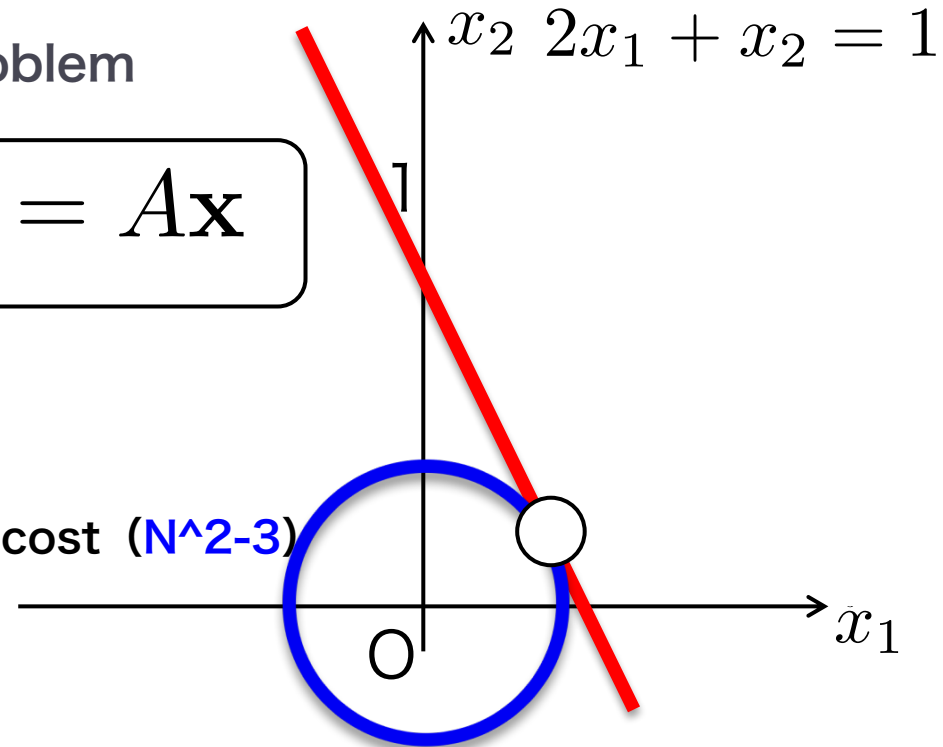


# Sparse signal inference

- ▶ L2 norm minimization
  - ▶ Much easier optimization problem

$$\min_{\mathbf{x}} \|\mathbf{x}\|_2 \quad \text{s.t.} \quad \mathbf{y} = A\mathbf{x}$$

- ▶ **Non-Sparse** solution
- ▶ **Convex optimization**
- ▶ Not expensive computational cost ( $N^2-3$ )



$$\|\mathbf{x}\|_2 = \sqrt{x_1^2 + x_2^2 + \cdots + x_N^2}$$



**L1 norm selects sparse solution**

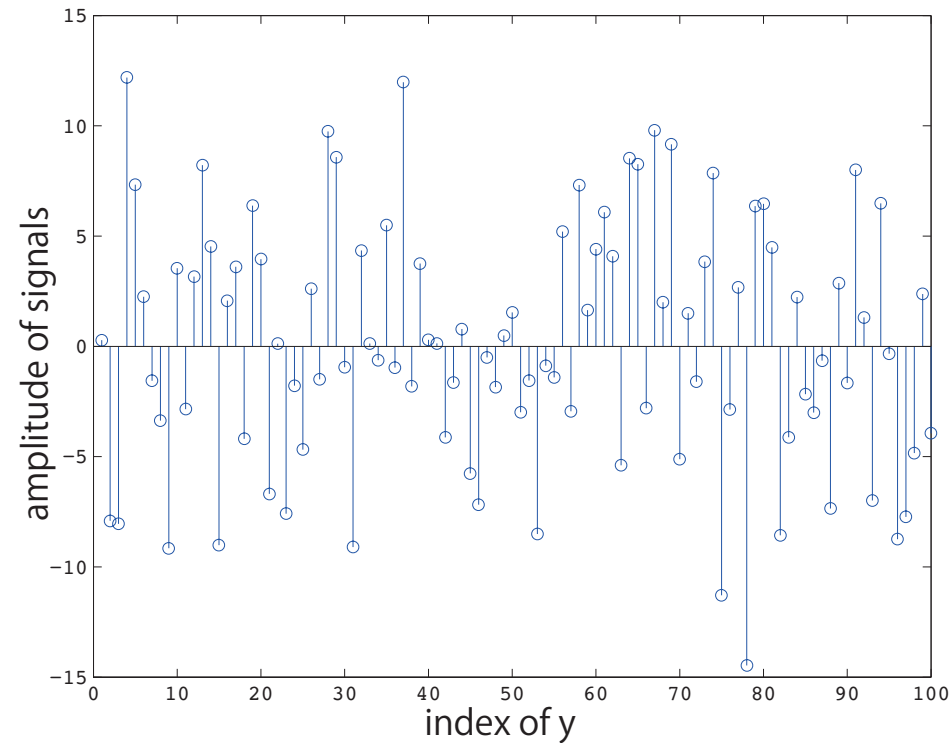
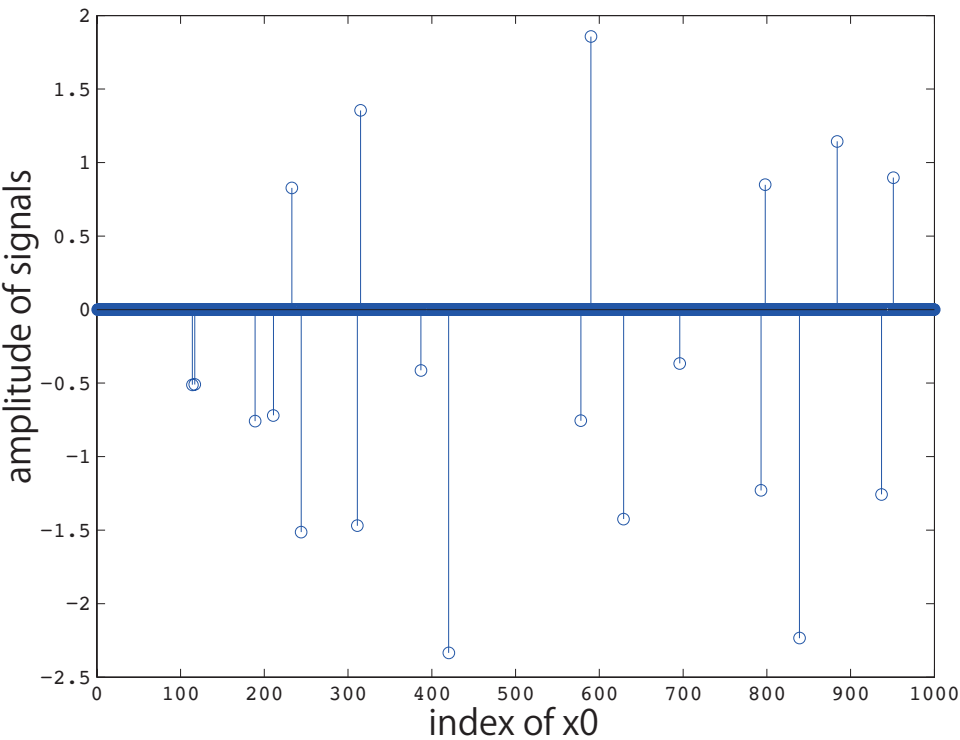


**L1 norm selects sparse solution**  
**Correct** or not?



# Example

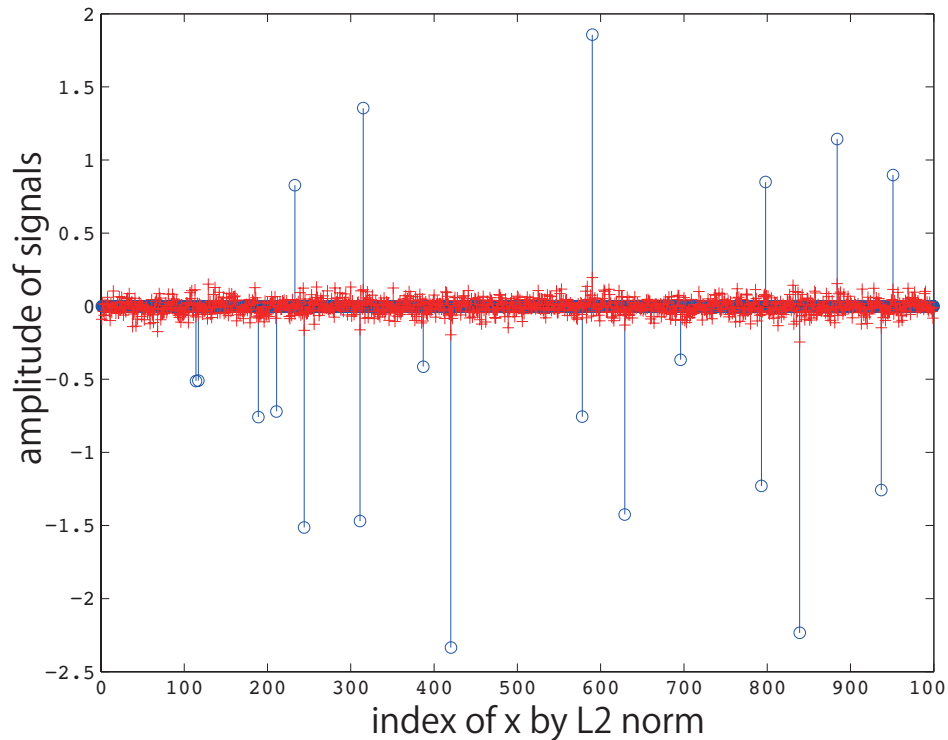
- ▶  $M=100, N=1000, K=20, A=\text{Gauss random matrix}$





# Example

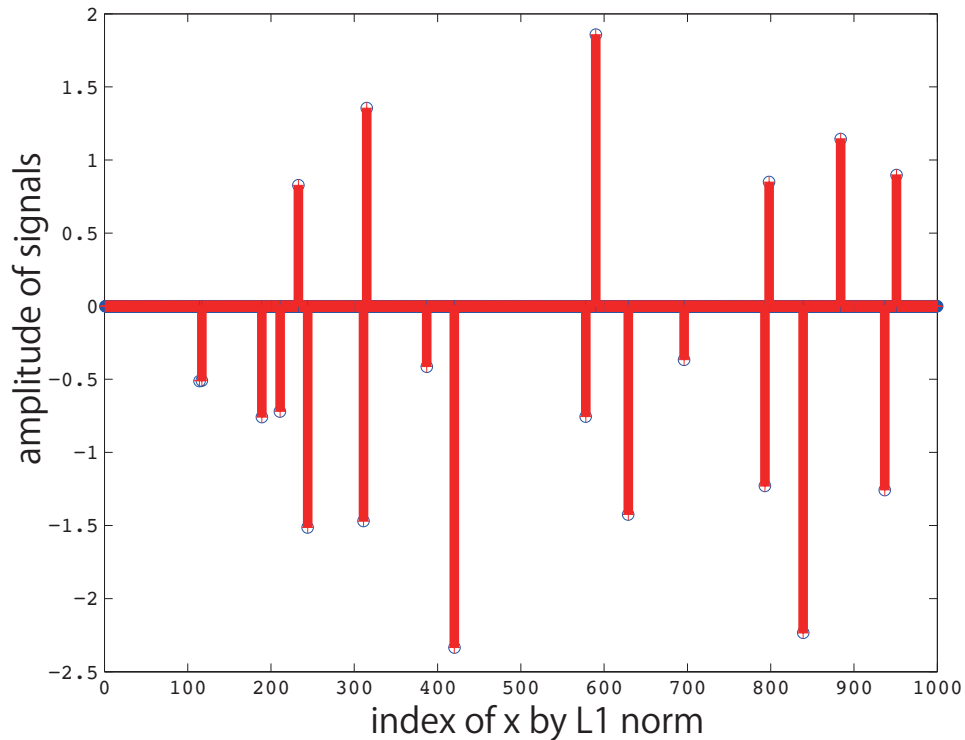
## ► L2 norm





# Example

## ► L1 norm





# L1 norm minimization

## ► Performance of **L1** norm minimization

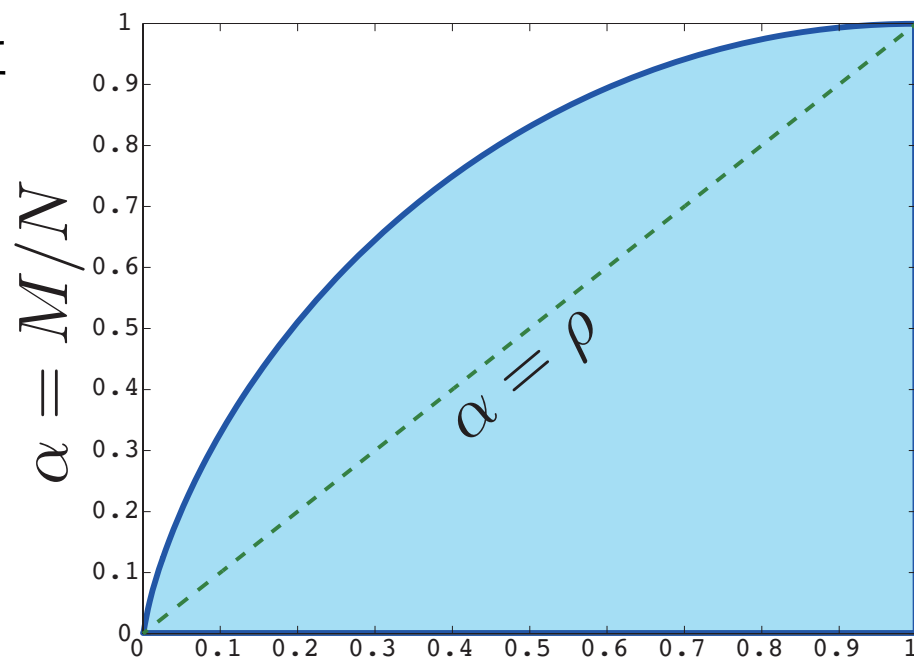
► Prescription :  $A$ =Gauss random matrix、 $x_0$ =Gauss random vector

$$\min_{\mathbf{x}} \|\mathbf{x}\|_1 \quad \text{s.t.} \quad \mathbf{y} = A\mathbf{x}$$

$$\frac{1}{\alpha} = 1 + \sqrt{\frac{\pi}{2}} t e^{\frac{t^2}{2}} \{1 - 2Q(t)\}$$

$$\frac{\rho}{1 - \rho} = 2 \left( \frac{e^{\frac{t^2}{2}}}{t\sqrt{2\pi}} - Q(t) \right)$$

$$Q(t) = \int_t^\infty \frac{e^{-\frac{x^2}{2}}}{\sqrt{2\pi}} dx$$



## ► Mathematics or **Statistical Physics**

[D. L. Dohono and J. Tanner: Proc. Nat. Acad. Sci. 102 (2005) 9452]

[Y. Kabashima, T. Wadayama, and T. Tanaka: J. Stat. Mech.: Theor. and Exp. 09 (2009) L09003]

$$\rho = K/N$$



**Sparse modeling**  
**Find  $x$  by sparsity**



**Sparse modeling**  
**Find  $x$  by sparsity**  
**Make  $x$  sparse**



How?  
Machine learning!

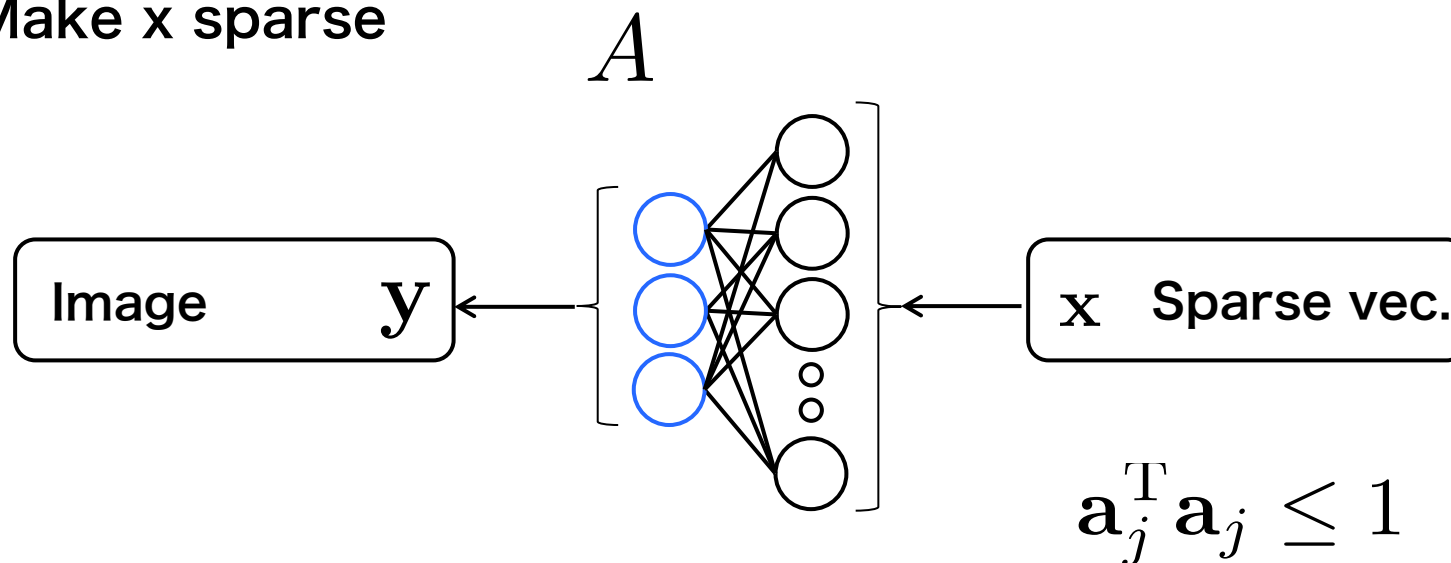
$$y = f(\mathbf{x})$$



# Dictionary learning

J. Mairal, F. Bach, F. Ponce, and G. Sapiro: ICML (2009)

- Make  $\mathbf{x}$  sparse



$$\min_{A, \mathbf{x}} \left\{ \frac{1}{2} \|\mathbf{y} - A\mathbf{x}\|_2^2 + \lambda \|\mathbf{x}\|_1 \right\}$$

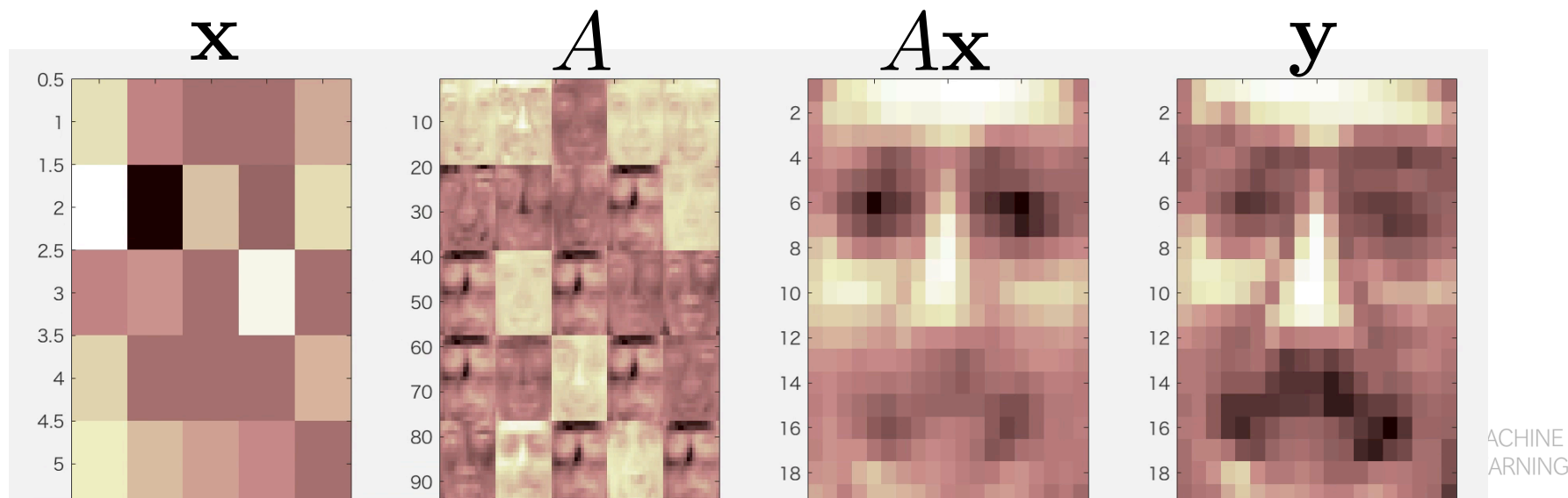
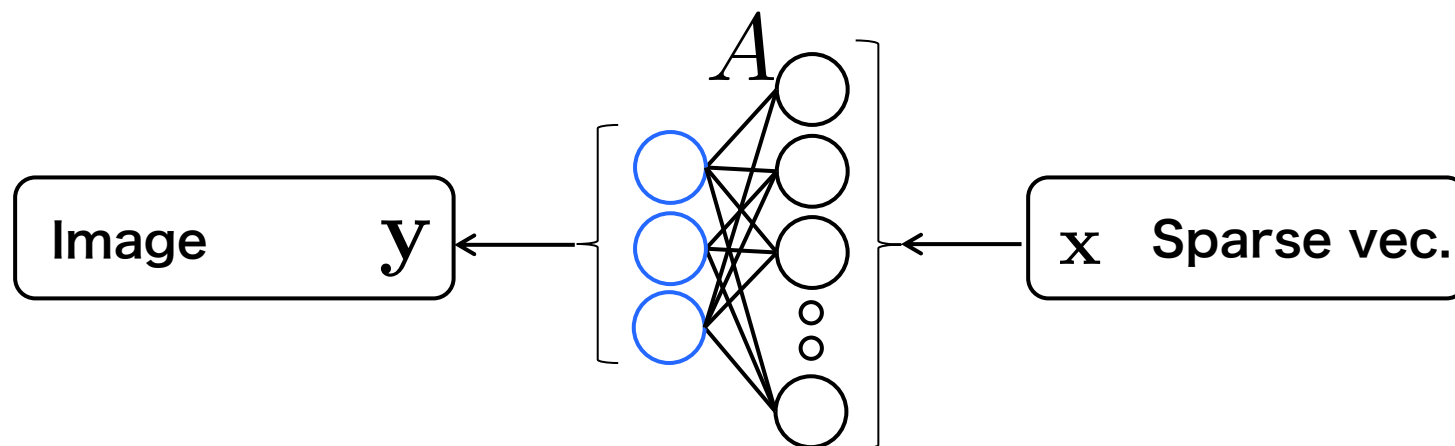
- Find  $A$  making  $\mathbf{x}$  sparse
- For Given  $\mathbf{y}$



# Dictionary learning

J. Mairal, F. Bach, F. Ponce, and G. Sapiro: ICML (2009)

- Make  $x$  sparse





# **Practical use of Compressed sensing**



# What is the problem?

## ► Solve the optimization problem

### ► Original problem

$$\min_{\mathbf{x}} \|\mathbf{x}\|_1 \quad \text{s.t.} \quad \mathbf{y} = A\mathbf{x}$$

### ► Penalty method

$$\min_{\mathbf{x}} \left\{ \frac{1}{2} \|\mathbf{y} - A\mathbf{x}\|_2^2 + \lambda \|\mathbf{x}\|_1 \right\}$$

#### ► LASSO (Least Absolute Shrinkage and Selection Operators)

#### ► Absolute value ? = **Not so difficult!**

$$\min_{\mathbf{x}} \left\{ \frac{1}{2} \|\mathbf{x} - \mathbf{v}\|_2^2 + \lambda \|\mathbf{x}\|_1 \right\}$$



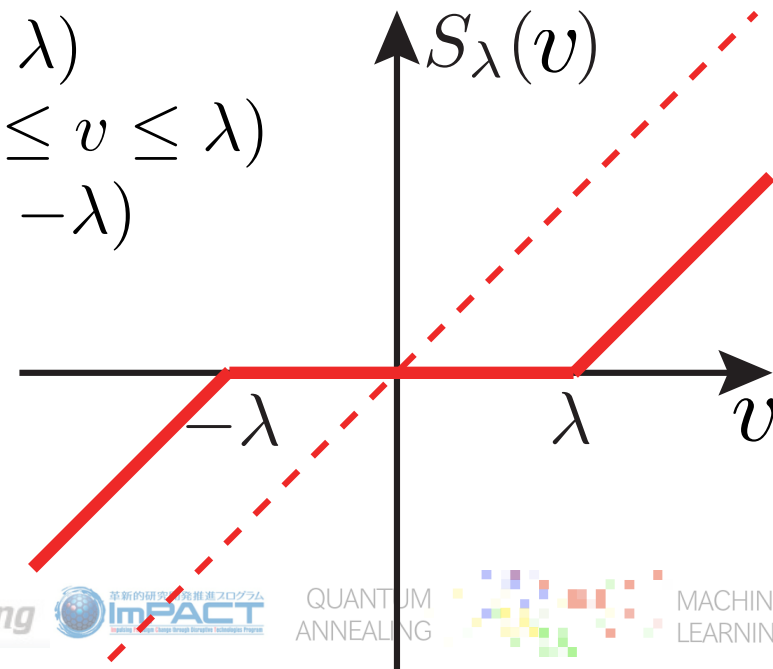
# Single-variable problem

## ► Soft-threshold function

$$\min_x \left\{ \frac{1}{2} (x - \textcolor{red}{v})^2 + \textcolor{blue}{\lambda} |x| \right\}$$

## ► Optimal value can be given by

$$x^* = S_{\textcolor{blue}{\lambda}}(\textcolor{red}{v}) = \begin{cases} v - \lambda & (v > \lambda) \\ 0 & (-\lambda \leq v \leq \lambda) \\ v + \lambda & (v < -\lambda) \end{cases}$$





# ADMM [Alternating Direction of Multiplier method]

S. Boyd, et al. **Foundation and Trends in Machine Learning**, 3 (2010) 1

- ▶ Change the problem by **augmented Lagrange method**
  - ▶ Combination of two cost function

$$\min_{\mathbf{x}} \{f(\mathbf{x}) + g(\mathbf{x})\}$$

- ▶ Ex) LASSO

$$f(\mathbf{x}) = \frac{1}{2} \|\mathbf{y} - A\mathbf{x}\|_2^2 \quad g(\mathbf{x}) = \lambda \|\mathbf{x}\|_1$$



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- ▶ **Splitting**

$$\min_{\mathbf{x}, \mathbf{z}} \{f(\mathbf{x}) + g(\mathbf{z})\} \quad \text{s.t.} \quad \mathbf{x} = \mathbf{z}$$



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- ▶ **Splitting**

$$\min_{\mathbf{x}, \mathbf{z}} \{f(\mathbf{x}) + g(\mathbf{z})\} \quad \text{s.t.} \quad \mathbf{x} = \mathbf{z}$$

- ▶ Augmented Lagrangian method (multiplier:  $\mathbf{h}$ , penalty:  $\rho$ )

$$\min_{\mathbf{x}, \mathbf{z}, \mathbf{h}} \left\{ f(\mathbf{x}) + g(\mathbf{z}) + \mathbf{h}^T (\mathbf{x} - \mathbf{z}) + \frac{\rho}{2} \|\mathbf{x} - \mathbf{z}\|_2^2 \right\}$$



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$$f(\mathbf{x}) = \frac{1}{2} \|\mathbf{y} - A\mathbf{x}\|_2^2 \quad g(\mathbf{x}) = \lambda \|\mathbf{x}\|_1$$

- ▶ **Alternation of optimization problem**

$$\begin{aligned} \min_{\mathbf{x}} & \left\{ f(\mathbf{x}) + \mathbf{h}^T(\mathbf{x} - \mathbf{z}) + \frac{\rho}{2} \|\mathbf{x} - \mathbf{z}\|_2^2 \right\} \\ \min_{\mathbf{z}} & \left\{ g(\mathbf{z}) + \mathbf{h}^T(\mathbf{x} - \mathbf{z}) + \frac{\rho}{2} \|\mathbf{x} - \mathbf{z}\|_2^2 \right\} \end{aligned}$$

- ▶ Update the multiplier  $\mathbf{h} = \mathbf{h} + \rho(\mathbf{x} - \mathbf{z})$



# ADMM [Alternating Direction of Multiplier method]

S. Boyd, et al. *Foundation and Trends in Machine Learning*, 3 (2010) 1

- ▶ Change the problem by **augmented Lagrange method**
  - ▶ Combination of two cost function

$$\min_{\mathbf{x}} \{f(\mathbf{x}) + g(\mathbf{x})\}$$

- ▶ Ex) LASSO

$$f(\mathbf{x}) = \frac{1}{2} \|\mathbf{y} - A\mathbf{x}\|_2^2 \quad g(\mathbf{x}) = \lambda \|\mathbf{x}\|_1$$

- ▶ **Alternation of optimization problem**

$$\min_{\mathbf{x}} \left\{ \frac{1}{2} \|\mathbf{y} - A\mathbf{x}\|_2^2 + \mathbf{h}^T(\mathbf{x} - \mathbf{z}) + \frac{\rho}{2} \|\mathbf{x} - \mathbf{z}\|_2^2 \right\}$$

$$\min_{\mathbf{z}} \left\{ \lambda \|\mathbf{z}\|_1 + \mathbf{h}^T(\mathbf{x} - \mathbf{z}) + \frac{\rho}{2} \|\mathbf{x} - \mathbf{z}\|_2^2 \right\}$$

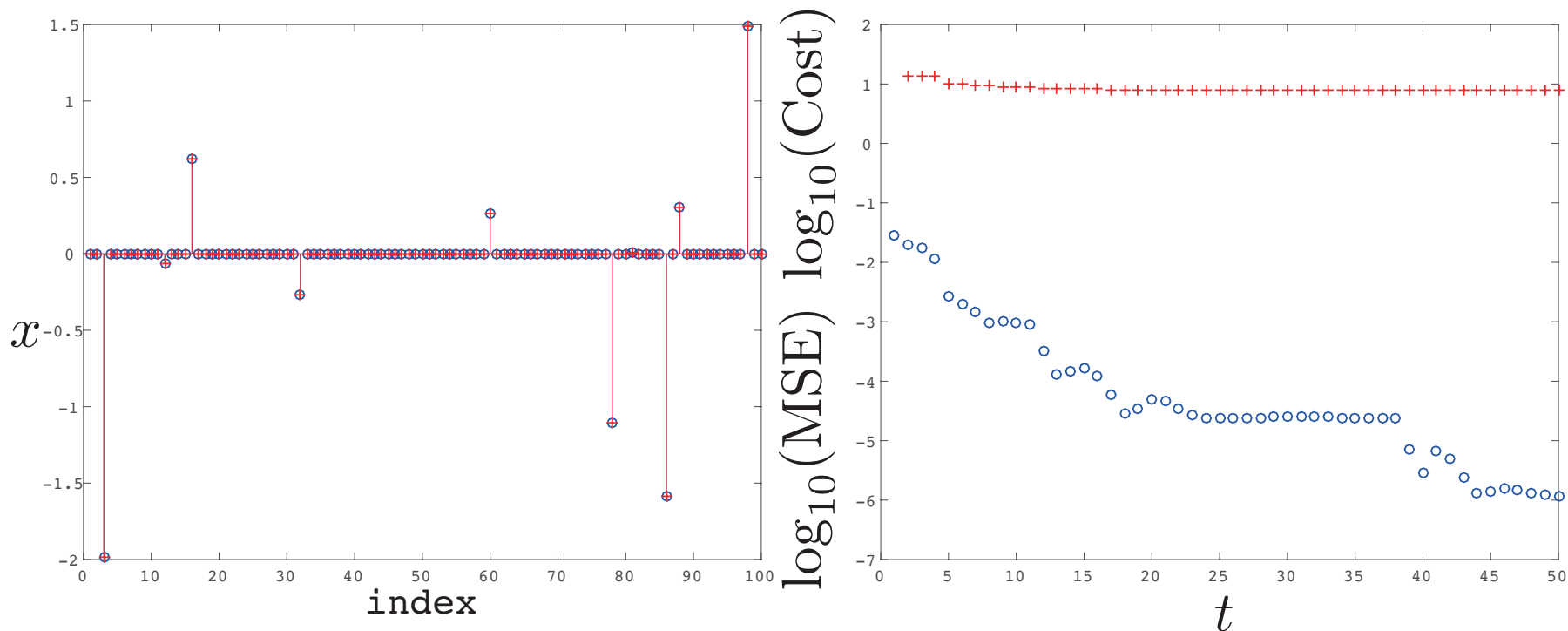
- ▶ Update the multiplier  $\mathbf{h} = \mathbf{h} + \rho(\mathbf{x} - \mathbf{z})$



# ADMM [Alternating Direction of Multiplier method]

S. Boyd, et al. *Foundation and Trends in Machine Learning*, 3 (2010) 1

ADMM (given by matlab code in pdf text)





# Summary

- ▶ Era for Data-driven science
  - ▶ Deep learning
    - ▶ To identify approximate form of function
    - ▶ Renormalization group analysis
  - ▶ Sparse modeling
    - ▶ To identify most relevant elements from input
    - ▶ Extract important structure in nature
- ▶ Application of two modern tools
  - ▶ To promote data-driven science
    - Compressed Sensing for recovery from small data
  - ▶ To search for new physics
    - Relevant elements from noisy quantum Monte-Carlo data

**J. Otsuki, M. Ohzeki, H. Shinaoka, and K. Yoshimi: Phys. Rev. E 95, 061302(R) (2017)**
    - Optimal orthogonal polynomial for analytical continuation

**H. Shinaoka, J. Otsuki, M. Ohzeki, and K. Yoshimi: arxiv:1702.03054**