Guiding Monte Carlo Simulations with Machine Learning

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References

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Outline

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1 Introduction to Markov Chain Monte Carlo

2 The Importance of Update

3 Example: Ising Model and Cluster Update

4 Example: Bosonic Model and Cumulative Update

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Monte Carlo simulation: an unbiased method

- A widely used numerical method in statistical physics and quantum many-body physics.
- Unbiased: reliable statistical error bar.
- Fast: error decreases as $1/\sqrt{\mathcal{N}}$.
- Universal: applies to any model without the sign program.

Introduction to MCMC

Consider a statistical mechanics model:

$$Z = \sum_{\mathcal{C}} e^{-\beta H[\mathcal{C}]} = \sum_{\mathcal{C}} W(\mathcal{C}).$$

- The Markov-chain Monte Carlo (MCMC) is a way to do importance sampling.
- A Markov chain is constructed,

$$\cdots \rightarrow \mathcal{C}_{i-1} \rightarrow \mathcal{C}_i \rightarrow \mathcal{C}_{i+1} \rightarrow \cdots$$

- Markov chain: $p(C_i \rightarrow C_j)$ only depends on C_i (no memory).
- Goal: distribution of C converges to the Boltzmann distribution W(C).
- Any observable can be measured from a Markov chain,

$$\langle O
angle = rac{\sum O(\mathcal{C})W(\mathcal{C})}{\sum W(\mathcal{C})} \simeq rac{1}{\mathcal{N}}\sum_i O(\mathcal{C}_i).$$

Detailed balance

• Detailed balance:

$$\frac{p(\mathcal{C}\to\mathcal{D})}{p(\mathcal{D}\to\mathcal{C})}=\frac{W(\mathcal{D})}{W(\mathcal{C})}.$$

- Detailed balance (and ergodicity) guarantees that IF the MC converges, it converges to the desired distribution W(C).
- Metropolis-Hastings algorithm: propose accept/reject.

$$p(\mathcal{C} o \mathcal{D}) = q(\mathcal{C} o \mathcal{D}) lpha(\mathcal{C} o \mathcal{D}).$$
 $lpha(\mathcal{C} o \mathcal{D}) = \min\left\{1, rac{W(\mathcal{D})}{W(\mathcal{C})} rac{q(\mathcal{D} o \mathcal{C})}{q(\mathcal{C} o \mathcal{D})}
ight\}.$

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Autocorrelation time

- Autocorrelation time measures the efficiency of the update algorithm.
- "time" sequence:

$$\cdots o O(t-1) o O(t) o O(t+1) o \cdots, \quad O(t) = O[\mathcal{C}(t)].$$

• Autocorrelation function

$$\mathcal{A}_O(\Delta t) = \langle O(t)O(t+\Delta t)
angle - \langle O(t)
angle^2 \propto e^{-\Delta t/ au}.$$

Complexity $\propto \tau$

$$\langle O
angle = rac{1}{\mathcal{N}} \sum_i O(\mathcal{C}_i).$$

Statistical error $\delta O \sim \frac{1}{\sqrt{N}}$ only if O(i) are independent.



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Metropolis algorithm



• Local update: randomly select a site and flip the spin.

•
$$q(\mathcal{C} \to \mathcal{D}) = q(\mathcal{D} \to \mathcal{C}) = \frac{1}{N}$$

- $\alpha(\mathcal{C} \to \mathcal{D}) = \min\left\{1, \frac{W(\mathcal{D})}{W(\mathcal{C})}\right\}.$
- *N* trials are counted as one MC step.
- Very general: applies to any model.
- N Metropolis, A W Rosenbluth, M N Rosenbluth, A H Teller, and E Teller, J Chem Phys 21, 1087 (1953).

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Critical slowing down

- The real dynamical relaxation time diverges at the critical point: a critical system is slow to equilibrate.
- The local update mimics the real relaxation process: also exhibits the critical slowing down phenomena.
- $\tau \propto L^z$, z = 2.125 for the 2D Ising model.



There's a way around this: MCMC simulation does not have to mimic the real dynamics...



- A cluster is built one bond at a time.
- Probability of activating a bond is cleverly designed, such that

$$rac{q(\mathcal{C} o \mathcal{D})}{q(\mathcal{D} o \mathcal{C})} = rac{W(\mathcal{D})}{W(\mathcal{C})}.$$

- Thus we have the ideal acceptance ratio $\alpha = 1$.
- Very efficient update: $\tau \sim L^{0.35}$.
- Only works with two-body interactions: $H = -\sum_{ij} J_{ij} s_i s_j$.
- U Wolff, PRL. 62, 361 (1989).



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Challenge

- Local update is too slow for many models: critical slowing down, glassy behavior, separation of energy scales, etc.
- Global update is only available for certain models. Like Wolff algorithm for two-body interactions.

• A good update algorithm for generic models?

A good update samples low-energy states



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- A dilemma of local updates:
- Step is too small: high acceptance, small difference.
- Step is too big: low acceptance, big difference.
- Global updates: explore the low-energy configurations.

A good update samples low-energy states



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- Global updates: explore the low-energy configurations.

A good update samples low-energy states



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- A dilemma of local updates:
- Step is too small: high acceptance, small difference.
- Step is too big: low acceptance, big difference.
- Global updates: explore the low-energy configurations.

Modeling the update process

- A stochastic function $f : C \mapsto D$.
- Parameterized: $f = f(p_1, p_2, \ldots, p_n)$.
- Analytically known $q(\mathcal{C} \stackrel{f}{\mapsto} \mathcal{D})$.
- Optimize *p_i*, such that

$$rac{q(\mathcal{C} \stackrel{f}{\mapsto} \mathcal{D})}{q(\mathcal{D} \stackrel{f}{\mapsto} \mathcal{C})} \simeq rac{W(\mathcal{D})}{W(\mathcal{C})}.$$

• Choose the acceptance ratio

$$\alpha(\mathcal{C} \to \mathcal{D}) = \min\left\{1, \frac{W(\mathcal{D})}{W(\mathcal{C})} \frac{q(\mathcal{D} \stackrel{f}{\mapsto} \mathcal{C})}{q(\mathcal{C} \stackrel{f}{\mapsto} \mathcal{D})}\right\} \simeq 1.$$

• The approximation $\frac{q(\mathcal{C} \stackrel{f}{\mapsto} \mathcal{D})}{q(\mathcal{D} \stackrel{f}{\mapsto} \mathcal{C})} \simeq \frac{W(\mathcal{D})}{W(\mathcal{C})}$ does not introduce error in the MC simulation, as long as we know $q(\mathcal{C} \stackrel{f}{\mapsto} \mathcal{D})$ accurately.

Design



Outline

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1 Introduction to Markov Chain Monte Carlo

2 The Importance of Update

3 Example: Ising Model and Cluster Update

4 Example: Bosonic Model and Cumulative Update

Example:

• The model:

$$H = -J_1 \sum_{\langle ij \rangle} s_i s_j - J_2 \sum_{ijkl \in \Box} s_i s_j s_k s_l.$$

• The effective model:

$$H_{
m eff} = -J_1^{
m eff} \sum_{\langle ij
angle} s_i s_j \, .$$

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- We consider $J_1 = 1$, $J_2 = 0.2$.
- An Ising transition at $T_c = 2.493$. Ising model without J_2 has $T_c = 2.269$.

The self-learning update

• The update: cluster is constructed using the effective model.

$$\frac{q(\mathcal{C} \to \mathcal{D})}{q(\mathcal{D} \to \mathcal{C})} = \frac{W_{\text{eff}}(\mathcal{D})}{W_{\text{eff}}(\mathcal{C})}.$$

• The acceptance ratio:

$$lpha(\mathcal{C} o \mathcal{D}) = \min\left\{1, rac{W(\mathcal{D})}{W(\mathcal{C})} rac{W_{\mathsf{eff}}(\mathcal{C})}{W_{\mathsf{eff}}(\mathcal{D})}
ight\}.$$

• The algorithm still satisfies the detailed balance exactly, although the effective model is approximate.

Learning the effective model

- 1. Generate a sample using the local update.
- 2. Perform a linear regression,

$$H_{\rm eff} = J_1^{\rm eff} \sum_{\langle ij \rangle} S_i S_j + E_0.$$



Unsupervised machine learning

- The linear regression we just did can be viewed as an unsupervised machine learning.
- Unsupervised ML: learning the underlying distribution from a sample of configurations.
- We pretend that we didn't know H, and learn a simpler model H_{eff} .
- The learned model describes the low-energy effective theory, where the high-energy fluctuations are treated as noise in the sample.
- Can incorporate more advanced ML models and algorithms.

Learning the effective model

- 1. Generate a sample using the local update, at $T = 5 > T_c$.
- 2. Perform a linear regression,

$$H_{ ext{eff}} = J_1^{ ext{eff}} \sum_{\langle ij
angle} S_i S_j + E_0.$$

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3. $J_1^{\text{eff}} = 1.0726.$

- 4. Generate another sample using the self-learning update, at $T = T_c$.
- 5. $J_1^{\text{eff}} = 1.1064.$

Autocorrelation time



System size 40×40 .

SLMC works well at moderate sizes



- The results look good at moderate sizes L = 20 80, but the scaling behavior is exponential...
- Eventually, the self-learning update becomes slower than the local update.

Limiting the cluster size

- $\Delta H = H H_{\text{eff}}$ scales with the perimeter of the cluster $\sim L$.
- $\tau \sim e^{L/L_0}$ because $\alpha \sim e^{-\beta \Delta H} \sim e^{-L/L_0}$.
- A simple effective model is not accurate: need more accurate model, with a hierarchy of energy scales.
- Quick fix: limit the cluster size during cluster growing. Still satisfies the detailed balance, if α is corrected correspondingly.
- A block update: same scaling as the local update, but with a smaller prefactor.

Restricted-cluster-size update



We restrict the cluster size to r = 40.

Summary



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Outline

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1 Introduction to Markov Chain Monte Carlo

2 The Importance of Update

3 Example: Ising Model and Cluster Update

4 Example: Bosonic Model and Cumulative Update

Determinant Monte Carlo: computational cost

• Fermion coupling to (auxiliary) bosonic field.

$$H = -\sum_{ij} t_{ij} c_i^{\dagger} c_j + \sum_i \sigma_i c_i^{\dagger} c_i + H[\sigma].$$

• Simulation: use bosonic field as configurations.

$$\mathcal{C} = \{\sigma_i(t)\}, i = 1, \dots, N; 0 < t < \beta.$$

- Weight of each configuration W(C): integrate out the fermions.
- Computational cost: βN^3 .
- Fast update: βN^3 for βN steps of local updates.
- Generating two independent configurations: $\beta N^3 \tau_L$.

Cumulative update

- Idea: replace $W(\mathcal{C})$ by $W'(\mathcal{C})$, which is much faster to evaluate.
- Local updates guided by $W'(\mathcal{C})$:

$$\mathcal{C} \Rightarrow \mathcal{D} : \mathcal{C} \to \mathcal{C}_1 \cdots \to \mathcal{C}_{i-1} \to \mathcal{C}_i \to \mathcal{C}_{i+1} \to \cdots \to \mathcal{C}_M \to \mathcal{D}.$$

• Detailed balance:

$$\frac{p(\mathcal{C}_i \to \mathcal{C}_{i+1})}{p(\mathcal{C}_{i+1} \to \mathcal{C}_i)} = \frac{W(\mathcal{C}_{i+1})}{W(\mathcal{C}_i)}$$

• For each path:

$$\frac{p(\mathcal{C} \to \mathcal{C}_1) \cdots p(\mathcal{C}_i \to \mathcal{C}_{i+1}) p(\mathcal{C}_M \to \mathcal{D})}{p(\mathcal{C}_1 \to \mathcal{C}) \cdots p(\mathcal{C}_{i+1} \to \mathcal{C}_i) p(\mathcal{D} \to \mathcal{C}_M)} = \frac{W'(\mathcal{C}_1)}{W'(\mathcal{C})} \frac{W'(\mathcal{C}_2)}{W'(\mathcal{C})} \cdots \frac{W'(\mathcal{C}_M)}{W'(\mathcal{C}_{M-1})} \frac{W'(\mathcal{D})}{W'(\mathcal{C}_M)} = \frac{W'(\mathcal{D})}{W'(\mathcal{C})}.$$

• Summing over all paths:

$$\frac{q(\mathcal{C}\to D)}{q(\mathcal{D}\to \mathcal{C})} = \frac{p(\mathcal{C}\Rightarrow D)}{p(\mathcal{D}\Rightarrow \mathcal{C})} = \frac{\sum_{\mathcal{C}_i} p(\mathcal{C}\to \mathcal{C}_1)\cdots p(\mathcal{C}_i\to \mathcal{C}_{i+1})p(\mathcal{C}_M\to \mathcal{D})}{\sum_{\mathcal{C}_i} p(\mathcal{C}_1\to \mathcal{C})\cdots p(\mathcal{C}_{i+1}\to \mathcal{C}_i)p(\mathcal{D}\to \mathcal{C}_M)} = \frac{W'(\mathcal{D})}{W'(\mathcal{C})}.$$

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Cumulative update

Approximated weight:

$$W'(\mathcal{C})\simeq W(\mathcal{C}).$$

• Update scheme:

$$rac{q(\mathcal{C} o D)}{q(\mathcal{D} o \mathcal{C})} = rac{W'(\mathcal{D})}{W'(\mathcal{C})} \simeq rac{W(\mathcal{D})}{W(\mathcal{C})}.$$

• Acceptance ratio:

$$\alpha(\mathcal{C} \to \mathcal{D}) = \min\left\{1, \frac{W(\mathcal{D})}{W(\mathcal{C})} \frac{W'(\mathcal{C})}{W'(\mathcal{D})}\right\} \simeq 1.$$

- Choose good W' and $M \ge \tau_L$: $\tau_{CU} \sim 1$.
- Computational cost: $\beta N^3 \tau \rightarrow \beta N^3$.
- Again, $W'(\mathcal{C}) \neq W(\mathcal{C})$ does not introduce approximation.

1. Physical intuition: bosonic effective model of $W_{\text{eff}}[\sigma]$ + Linear Regression. Works best for gapped fermions.

$$egin{aligned} \mathcal{H} = -\sum_{ij} t_{ij} c^{\dagger}_{ilpha} c_{jlpha} + \sum_i \sigma_i c^{\dagger}_{ilpha} \sigma^{z}_{lphaeta} c_{ieta} + \mathcal{H}[\sigma] \ W_{\mathsf{eff}}[\sigma] = \sum_{ij} J_{ij} \sigma_i \sigma_j. \end{aligned}$$

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2. Machine Learning models: Restricted Boltzmann Machine, Neural Networks, etc.

Self-Learning MC in action

- Zi-Hong Liu, Xiao-Yan Xu, Yang Qi, Kai Sun and Zi-Yang Meng, to appear.
- Fermion + boson model, new critical universality. Simulated at the critical point.
- SLMC: $L = 20 \rightarrow 30$.

